

Mobility Issues for LVSR

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REPORT DOCUMENTATION PAGE

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14. ABSTRACT The purpose of this analysis was to identify vehicle parameters and terrain features that impede mobility, to forecast mobility over different mission areas of interest, and to identify vehicle parameter modifications that will improve LVSR mobility performance.						
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Purpose

- Implement Stochastic Mobility Modeling methodologies that assist in assessing/developing LVSR.

Scope

- Use Stochastic Mobility Modeling to identify vehicle parameters and terrain features that impede mobility.
- Forecast mobility over different mission areas of interest.
- Identify vehicle parameter modifications which will improve LVSR mobility performance.

NRMMII Summary

NRMMII - A computer-based collection of equations and algorithms designed to predict the steady-state operating capability of a given vehicle in a prescribed terrain.

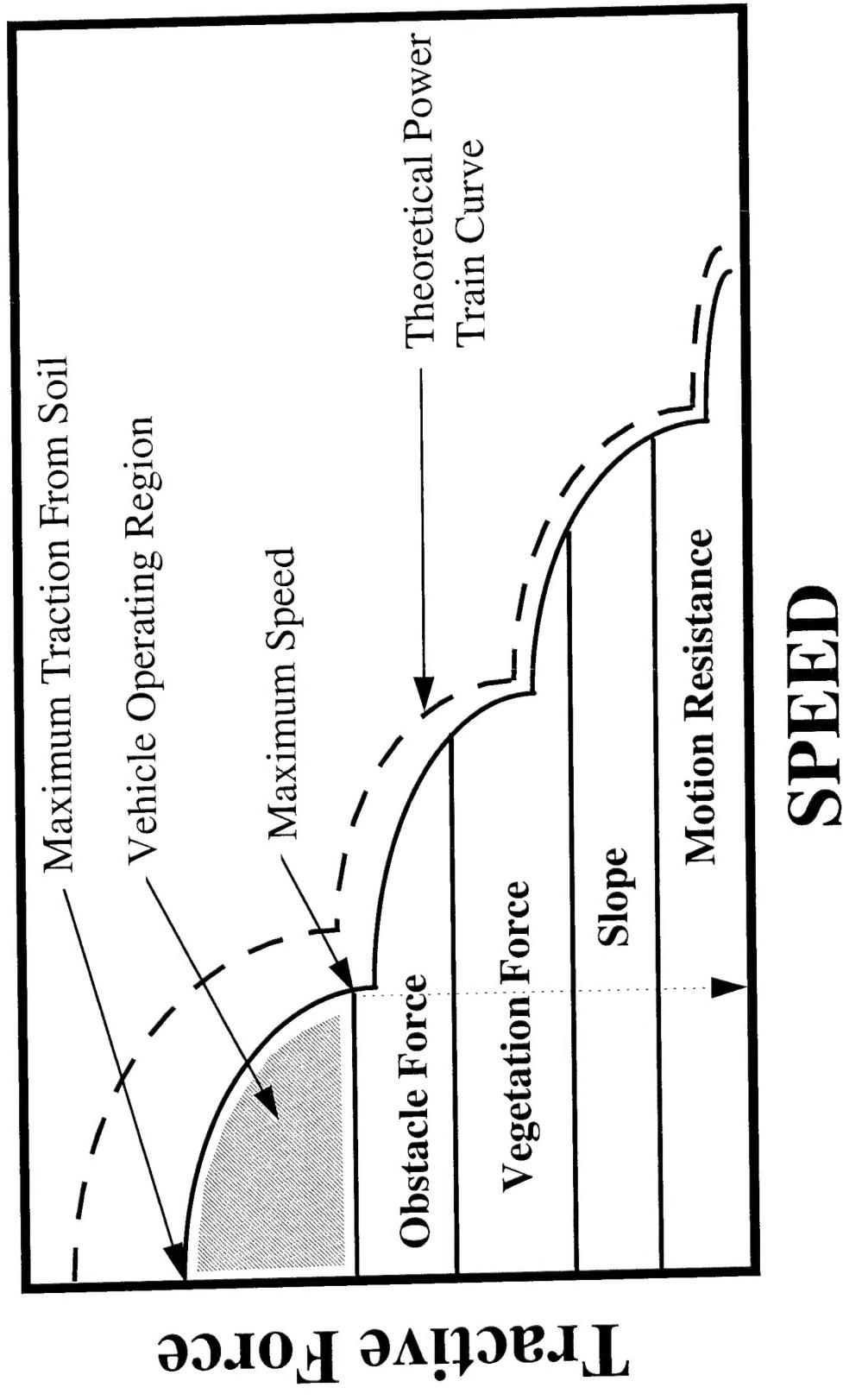
Areas

- Philippines (Mindanao Island)
- South Korea (Eastern Coast)
- Saudi Arabia/Kuwait (Eastern Coast)

Scenarios

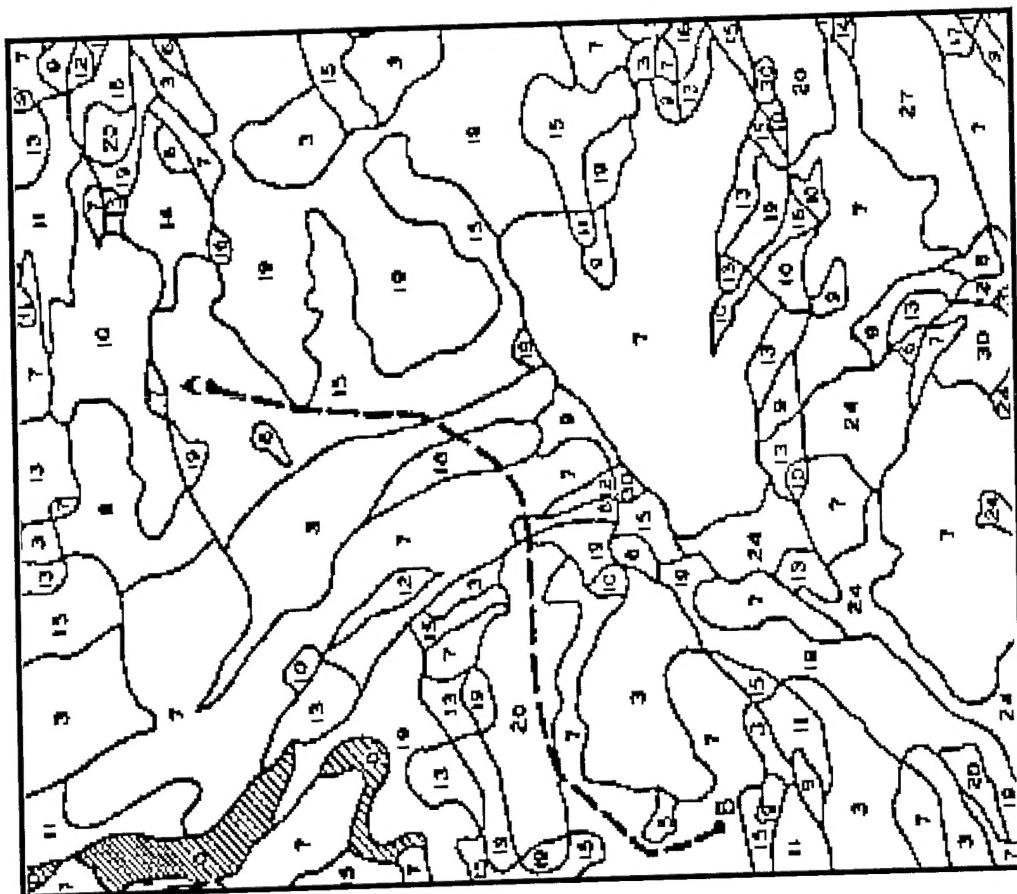
- Dry Normal
 - Average soil strength and moisture for the 30 driest days in an average rainfall year
- Wet Slippery
 - Average soil strength and moisture for the 30 wettest days in an average rainfall year

Tractive Force Speed Curve



Terrain Unit Mapping

Waterways Experiment Station



Terrain Parameters

- Surface Roughness
- Soil Depth to Bedrock
- Road Super-elevation
- Road Radius of Curvature
- Slope Percent
- Obstacle Approach Angle
- Obstacle Height
- Obstacle Length
- Obstacle Spacing
- Obstacle Width
- Soil Strength
- Recognition Distance
- Stem Diameter
- Standing Water Depth

Significant Vehicle Parameters

Vehicle Geometry

ACD	Aerodynamic drag coefficient.
EYEHGT	Driver's eye-height above ground.
PBF	Maximum pushbar force vehicle can withstand overriding vegetation.
PBHT	Height of pushbar above ground.
PFA	Vehicle projected frontal area.
TL	Vehicle length from 1st wheel to last wheel.
VULEN	Length of each vehicle unit.
WDTH	Maximum combination vehicle width.

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Traction Components

DFLCT	Tire Deflection for each assembly an deflection case.
DIAW	Undeflected tire diameter for each assembly.
SECTW	Tire nominal section width.
VTIRMX	Maximum tire speed limit for each deflection scenario.

Suspension

VRIDE	Limited speeds for RMS roughness versus limited speed data.
VOOB	Limiting speeds for obstacle height versus 2.5 G limited speed data.

Power Train

CID	Engine displacement.
FD	Final drive gear ratio and efficiency.
QMAX	Maximum net torque from each engine.
REVM	Tire revolutions per mile for each assembly.
TCASE	Engine to torque-converter gear ratio and efficiency.
TRANS	Transmission gear ratios and efficiencies.
XBRCOF	Combination vehicle braking coefficient.

Weight beneath each vehicle assembly.

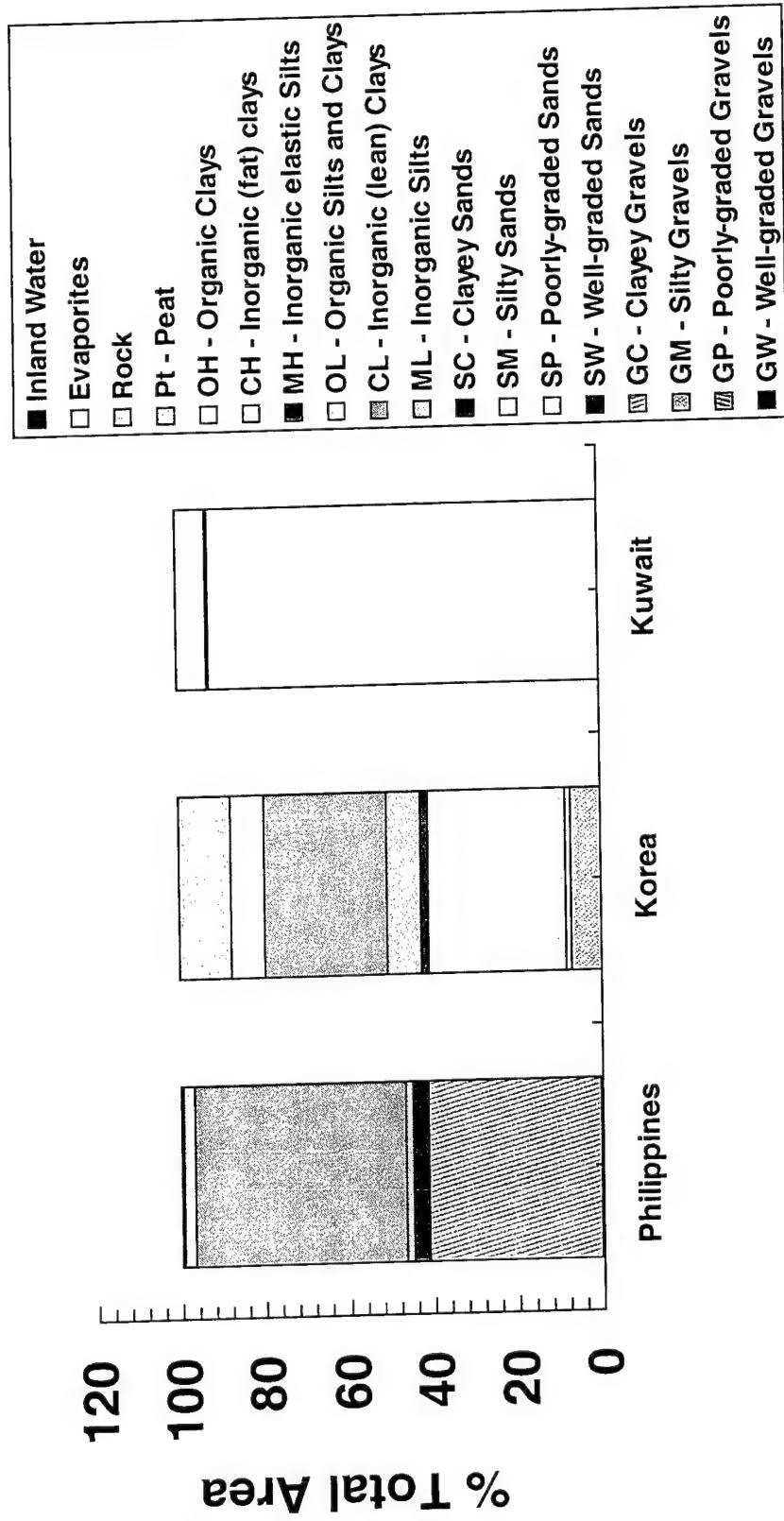
NRMMI "NOGO" Reason Codes

- Visibility
- Soil and Slope Resistance
- Obstacle Clearance Interference
- Obstacle Belly Interference
- Vegetation Override
- Obstacle Override
- Soil NO-GO
- Sliding
- Tipping

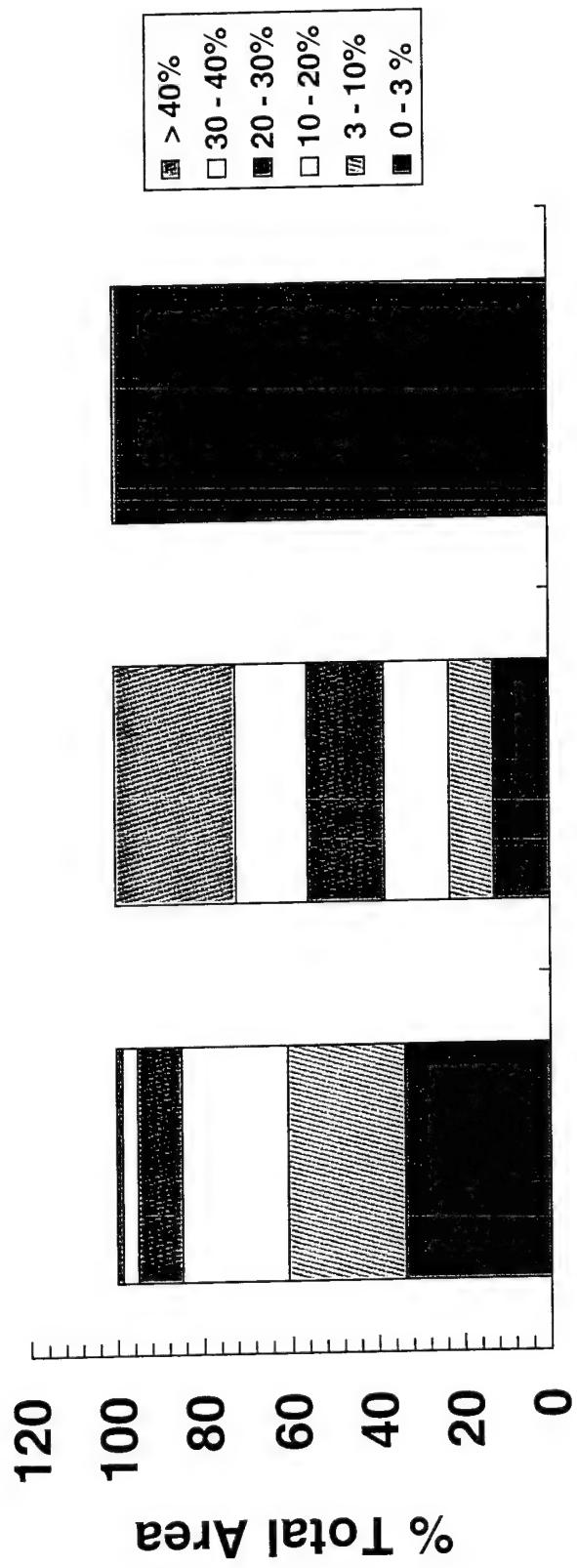
NRMMI "GO" Reason Codes

- Ride Dynamics Limit
- Tire Speed Limit
- Soil, Slope, & Veg Resistance
- Visibility
- Maneuver Around Obst and Veg
- Maneuver Around Veg
- Obstacle Impact Speed
- Obstacle Override Force
- Driver Prudence Over Veg
- Sliding on Curves
- Tipping on Curves

Soil Type Distributions for the Three Study Area

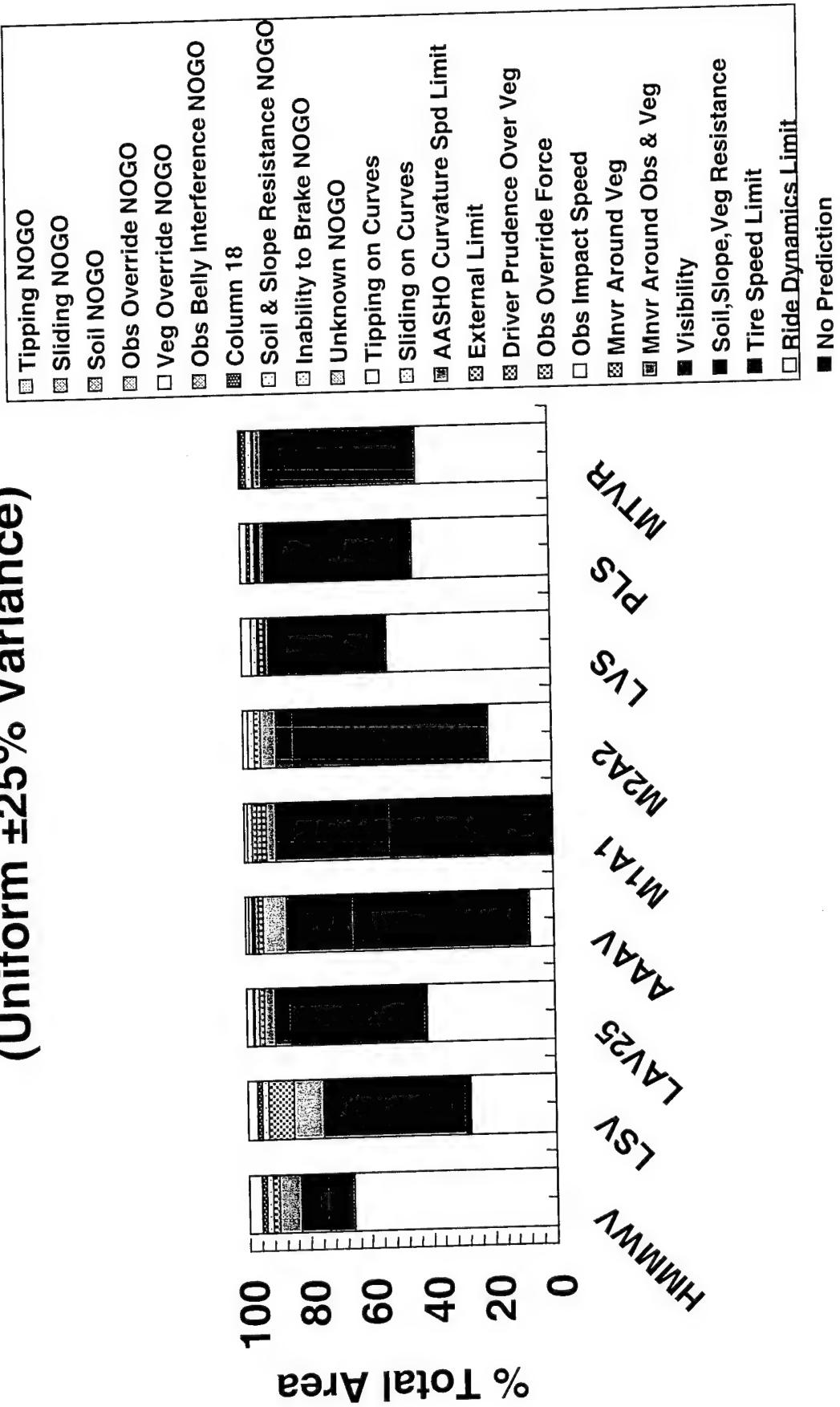


Slope Distributions for the Three Study Areas

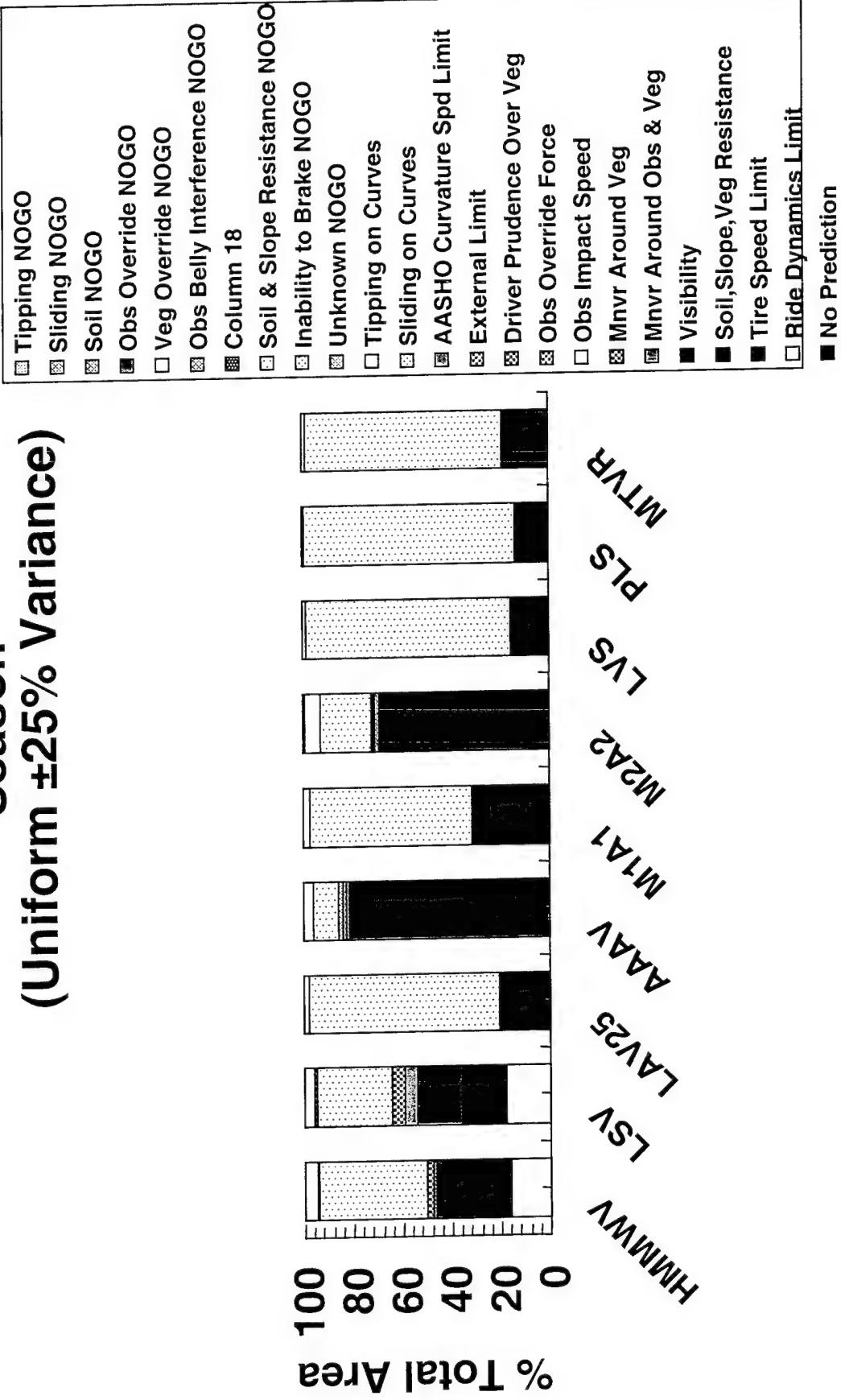


Philippines for Off-Road and Dry-Normal Season

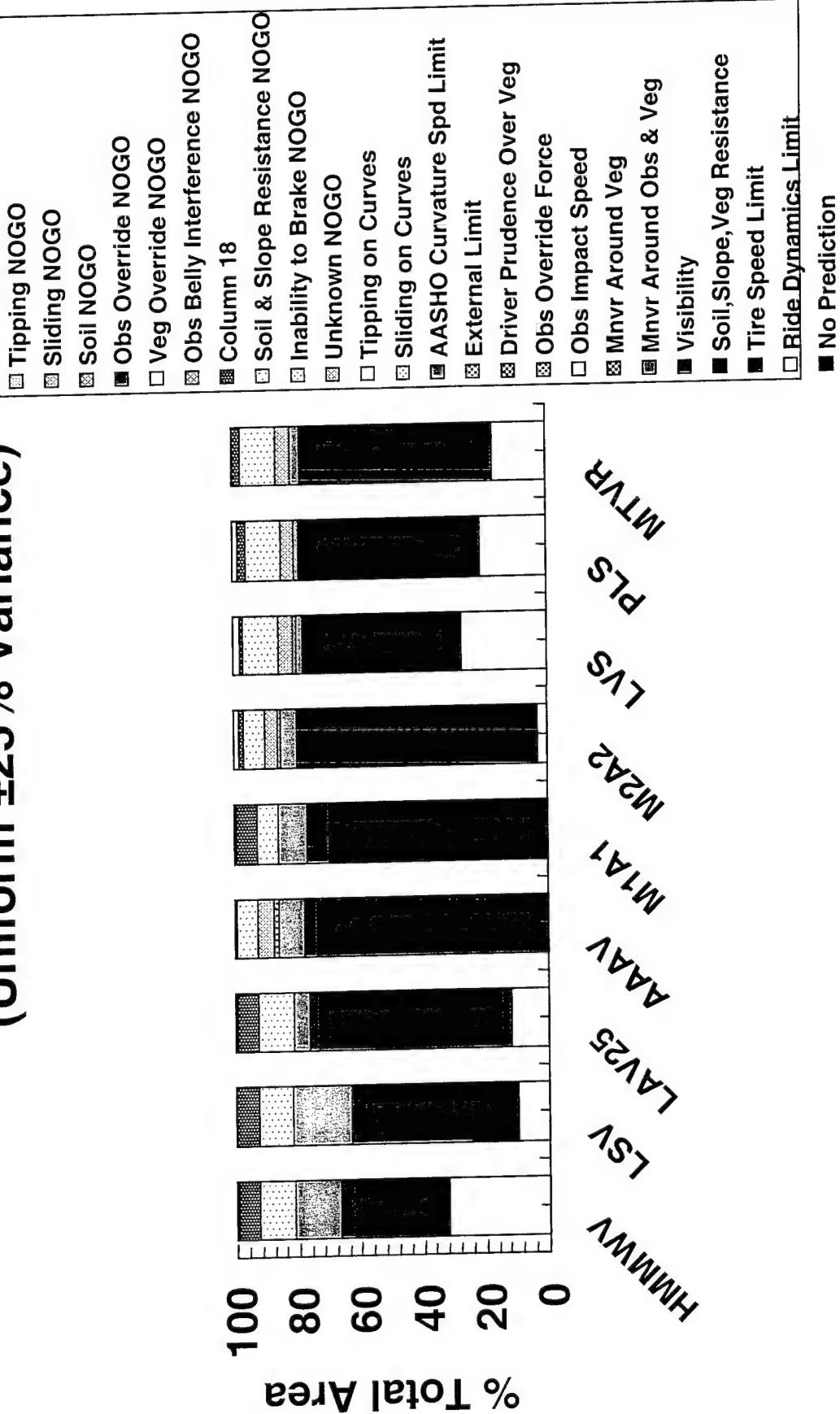
(Uniform $\pm 25\%$ Variance)



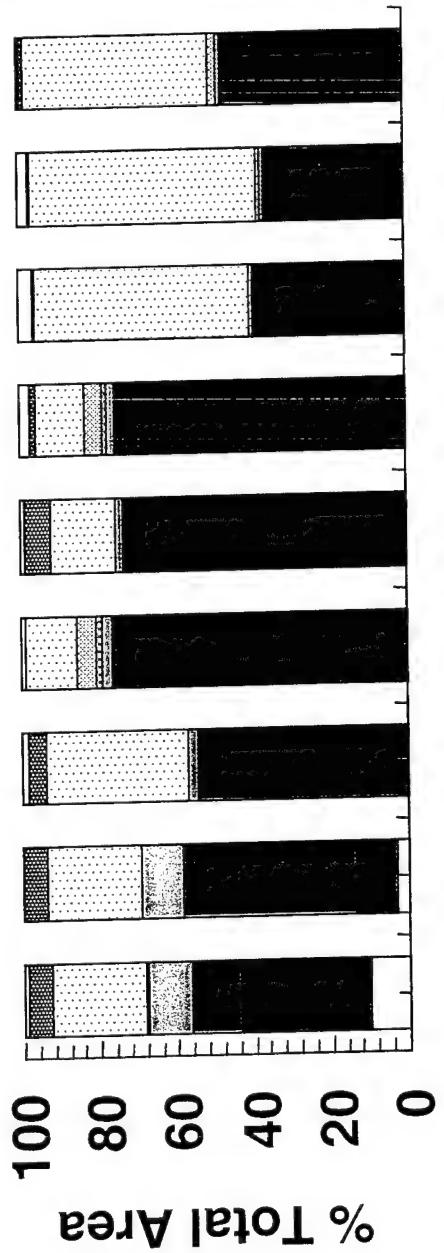
Philippines for Off-Road and Wet-Slippery Season (Uniform $\pm 25\%$ Variance)



Korea for Off-Road and Dry-Normal Season (Uniform $\pm 25\%$ Variance)



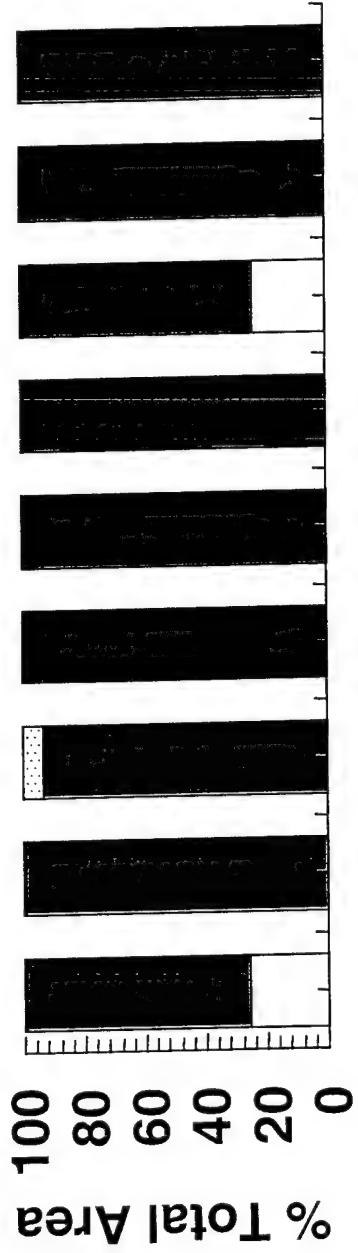
Korea for Off-Road and Wet-Slippery Season (Uniform $\pm 25\%$ Variance)



Waterways Experiment Station

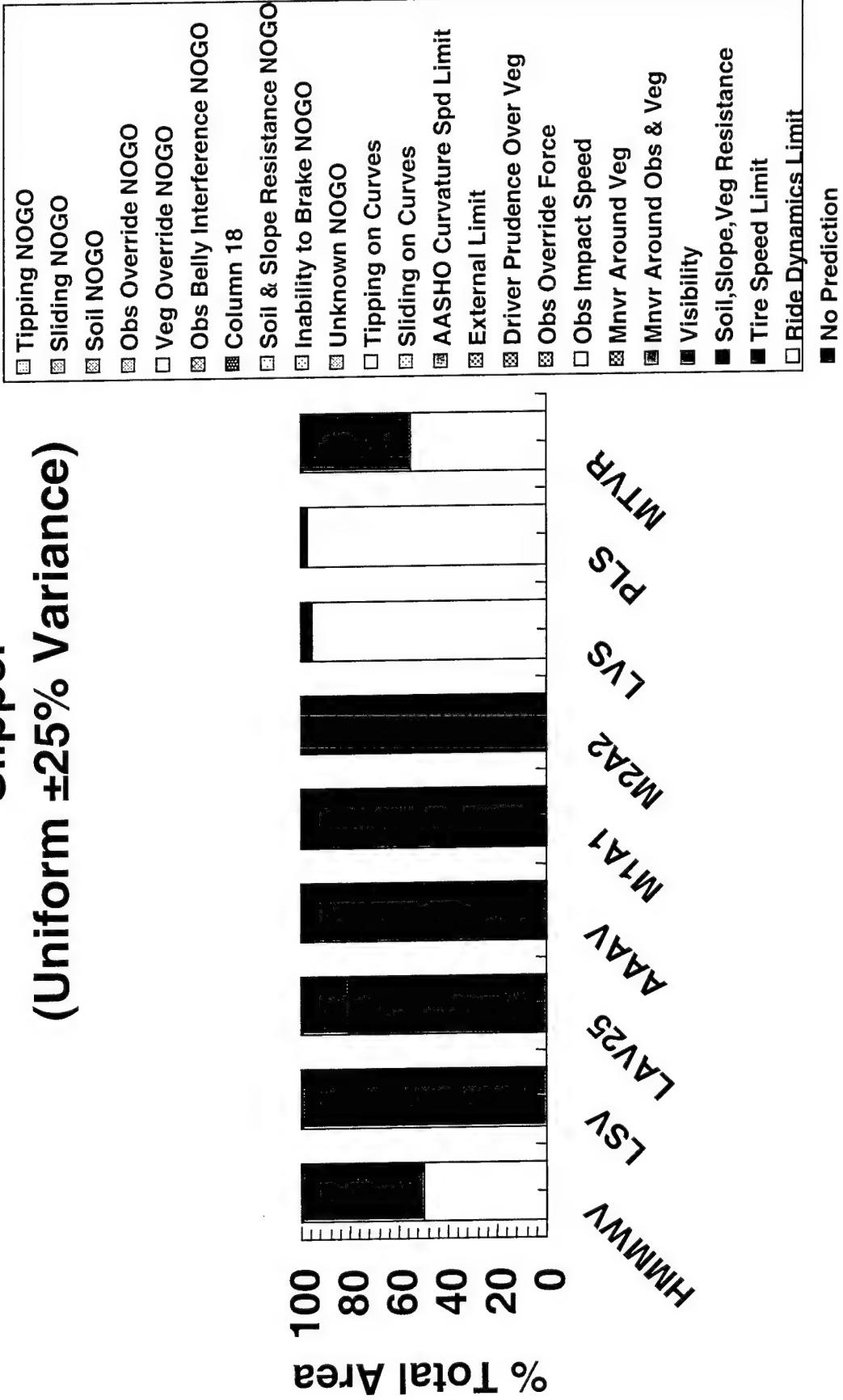
Saudi Arabia/Kuwait for Off-Road and Dry- Normal (Uniform $\pm 25\%$ Variance)

<input type="checkbox"/> Tipping NOGO	<input type="checkbox"/> Sliding NOGO	<input type="checkbox"/> Soil NOGO
<input type="checkbox"/> Obs Override NOGO	<input type="checkbox"/> Veg Override NOGO	<input type="checkbox"/> Obs Belly Interference NOGO
<input type="checkbox"/> Column 18	<input type="checkbox"/> Soil & Slope Resistance NOGO	<input type="checkbox"/> Inability to Brake NOGO
<input type="checkbox"/> Unknown NOGO	<input type="checkbox"/> Tipping on Curves	<input type="checkbox"/> Sliding on Curves
<input type="checkbox"/> AASHO Curvature Spd Limit	<input type="checkbox"/> External Limit	<input type="checkbox"/> Driver Prudence Over Veg
<input type="checkbox"/> Obs Override Force	<input type="checkbox"/> Obs Impact Speed	<input type="checkbox"/> Mnvr Around Veg
<input type="checkbox"/> Mnvr Around Obs & Veg	<input type="checkbox"/> Visibility	<input type="checkbox"/> Soil,Slope,Veg Resistance
<input type="checkbox"/> Tire Speed Limit	<input type="checkbox"/> Ride Dynamics Limit	<input type="checkbox"/> No Prediction



Saudi Arabia/Kuwait for Off-Road and Wet-Slipper

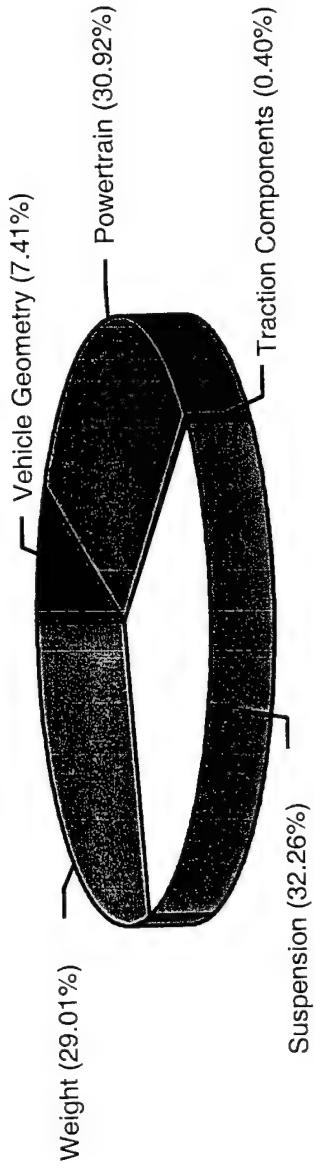
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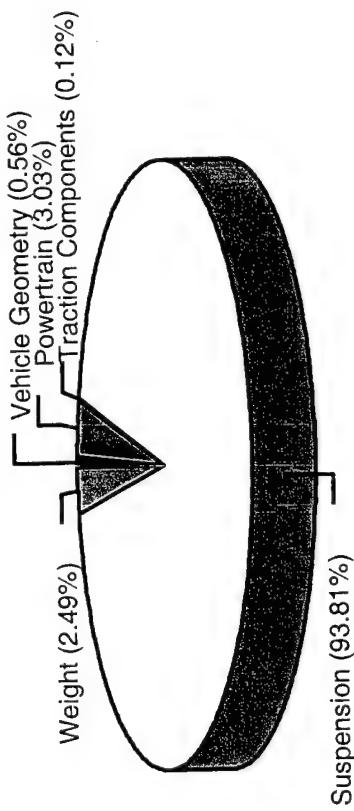
Significant LVIS Vehicle Parameters

Philippines, Off-Road, 20% Variance

DRY NORMAL



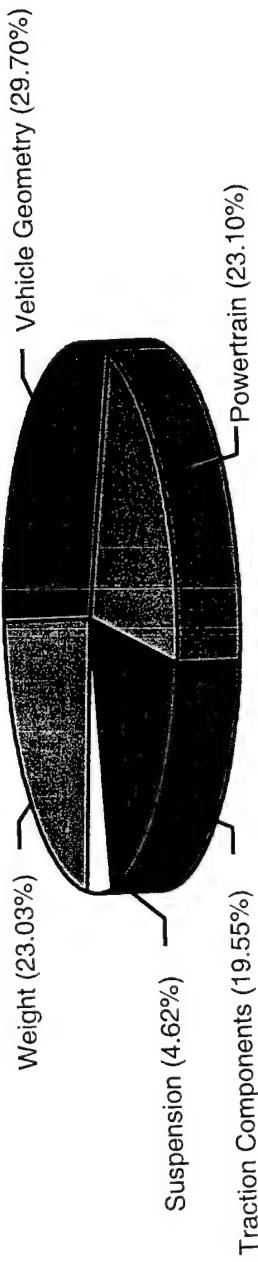
WET SLIPPERY



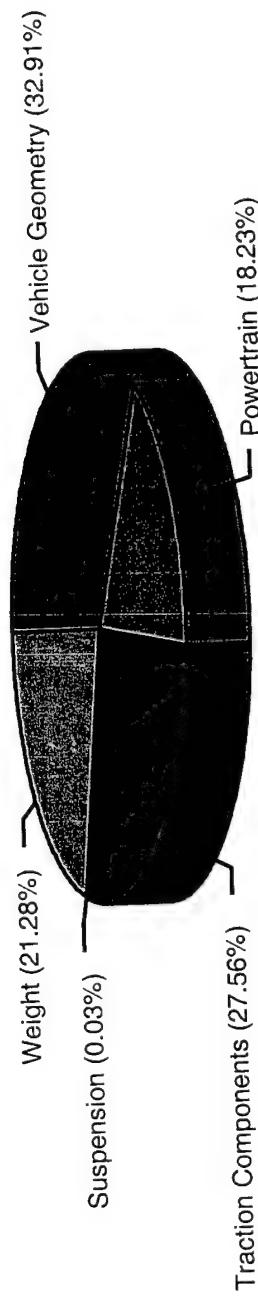
Significant LVSR Vehicle Parameters

South Korea, Off-Road, 20% Variance

DRY NORMAL

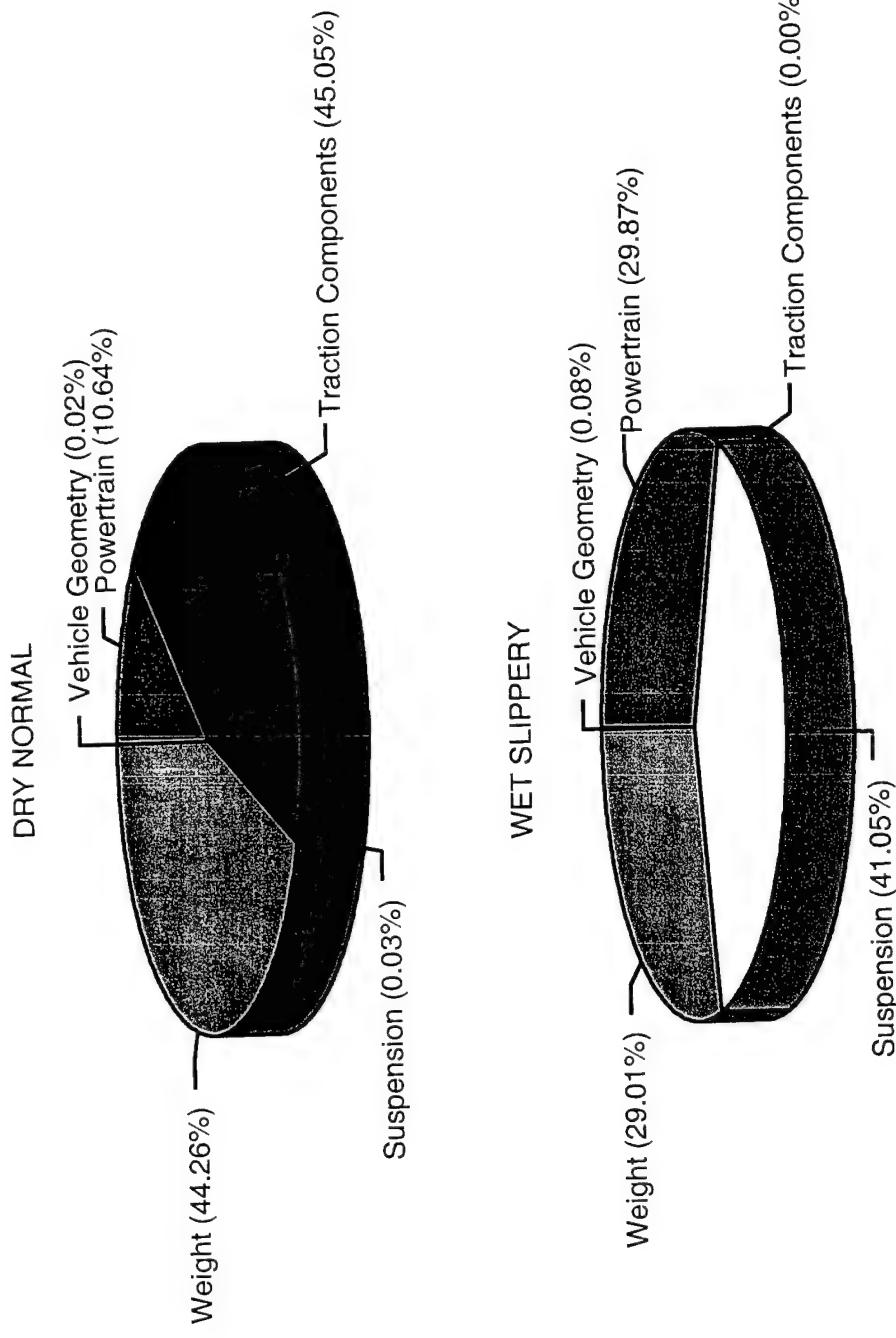


WET SLIPPERY



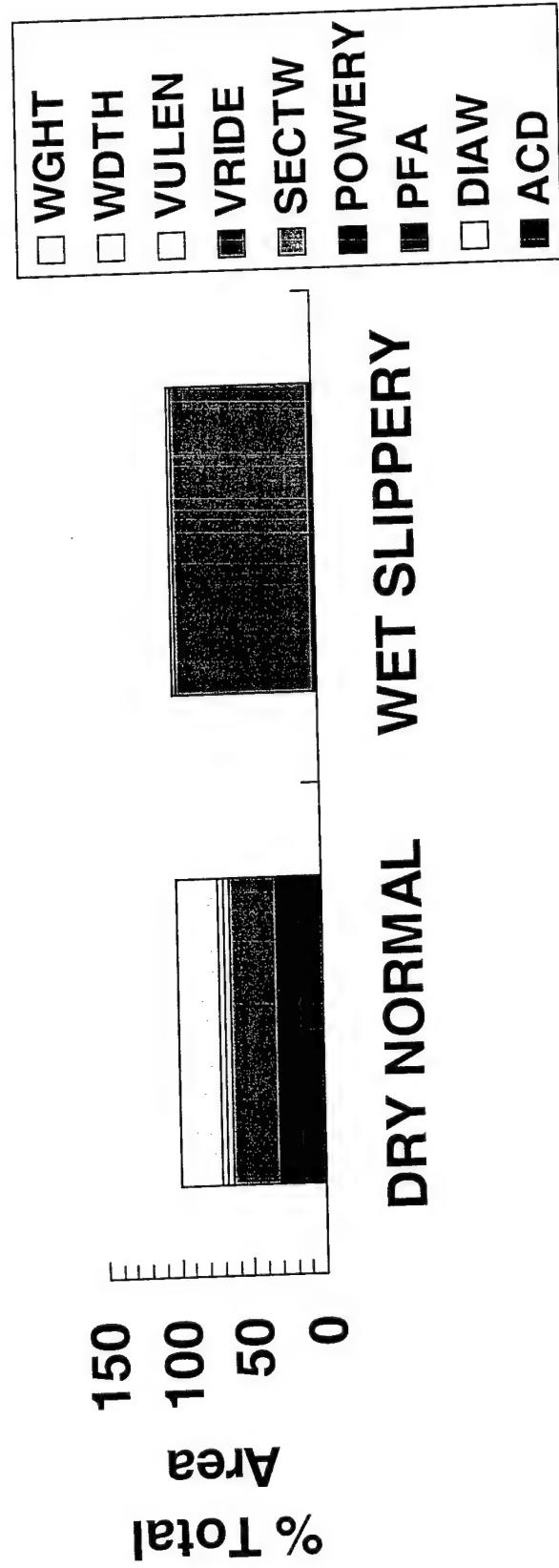
Significant LVs Vehicle Parameters

Kuwait, Off-Road, 20% Variance



Significant LVSR Vehicle Parameters

Mindanao, Philippines, Off-Road, 20% Variance

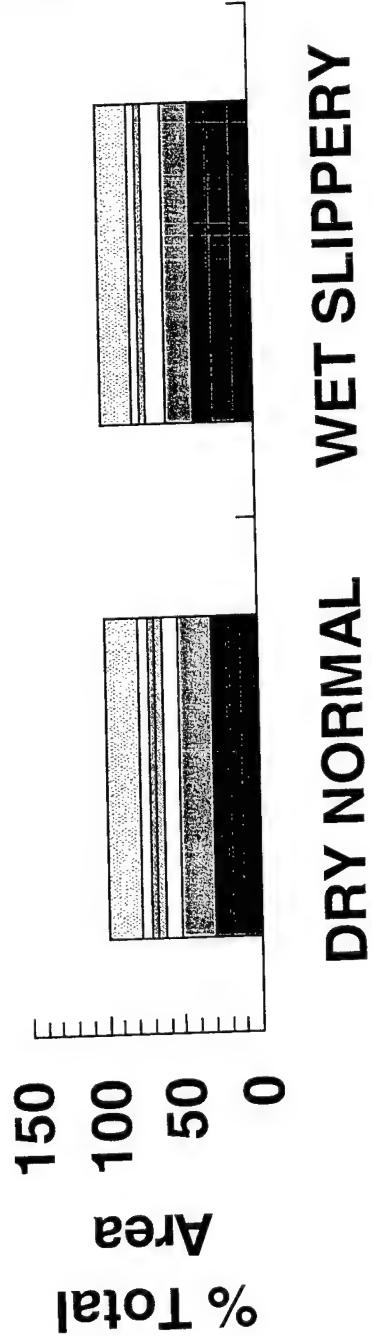


Significant LVSR Vehicle

Parameters

3421i, South Korea, Off-Road, 20% Variance

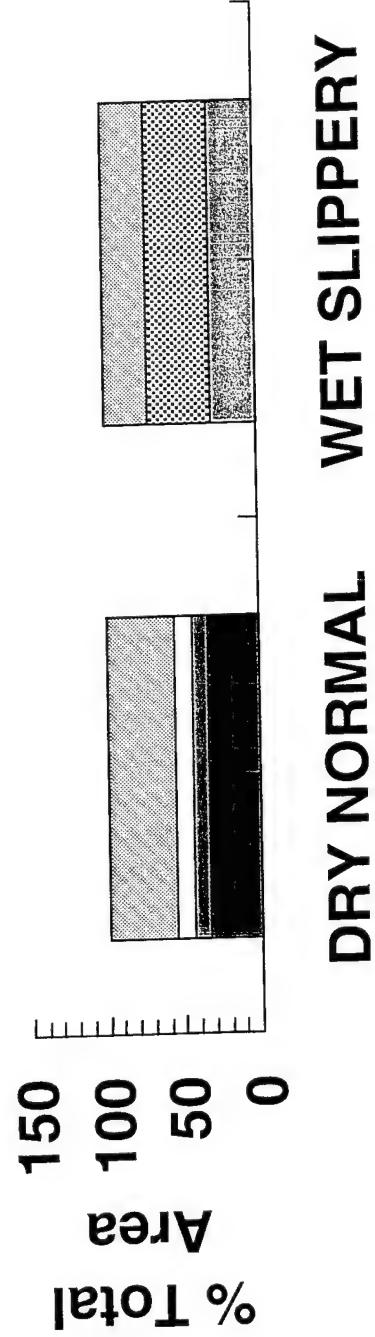
- XBRCOF
- WGHT
- WDTH
- VULEN
- VRIDE
- VOOB
- TL
- SECTW
- REVW
- QMAX
- POWERY
- PFA
- DIAW
- CID
- ACD



Significant LVSR Vehicle Parameters

5546i, Saudi Arabia/Kuwait, Off-Road, 20% Variance

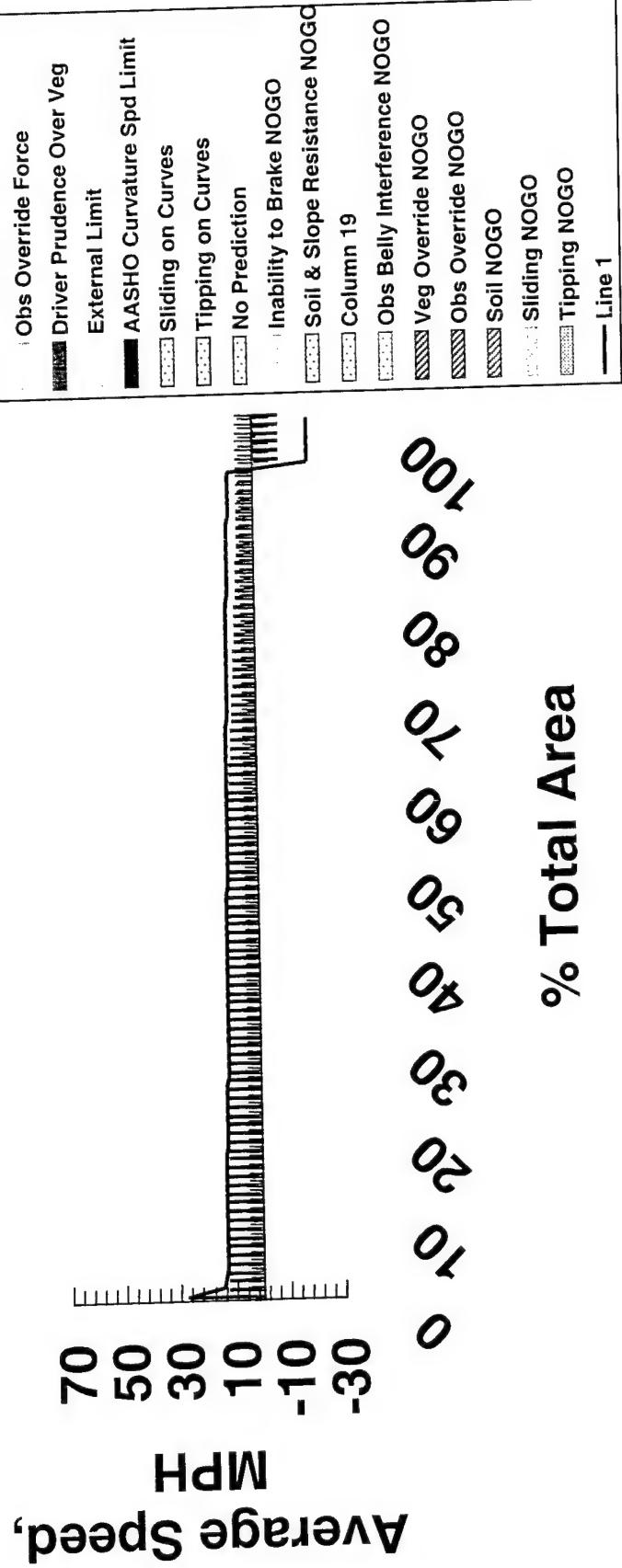
- XBRCOF
- WGHT
- VRIDE
- VOOB
- TL
- SECTW
- REVW
- QMAX
- POWERY
- PFA
- DIAW
- CID
- ACD



LvS Speed/Reason Profile Mindanao, Philippines, Off-Road, 100 Iterations

Dry Normal 50th Percentile Speed ($\pm 25\%$)

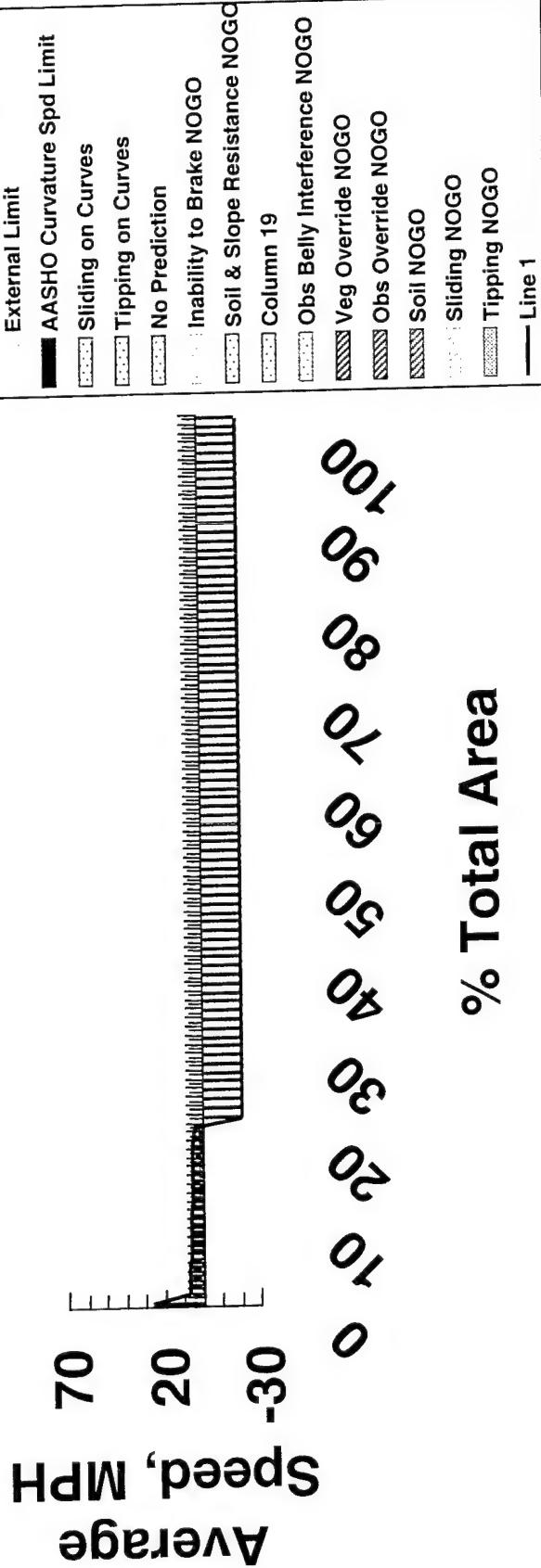
Waterways Experiment Station



LVIS Speed/Reason Profile Mindanao, Philippines, Off-Road, 100 Iterations

Wet Slippery 50th Percentile Speed ($\pm 25\%$)

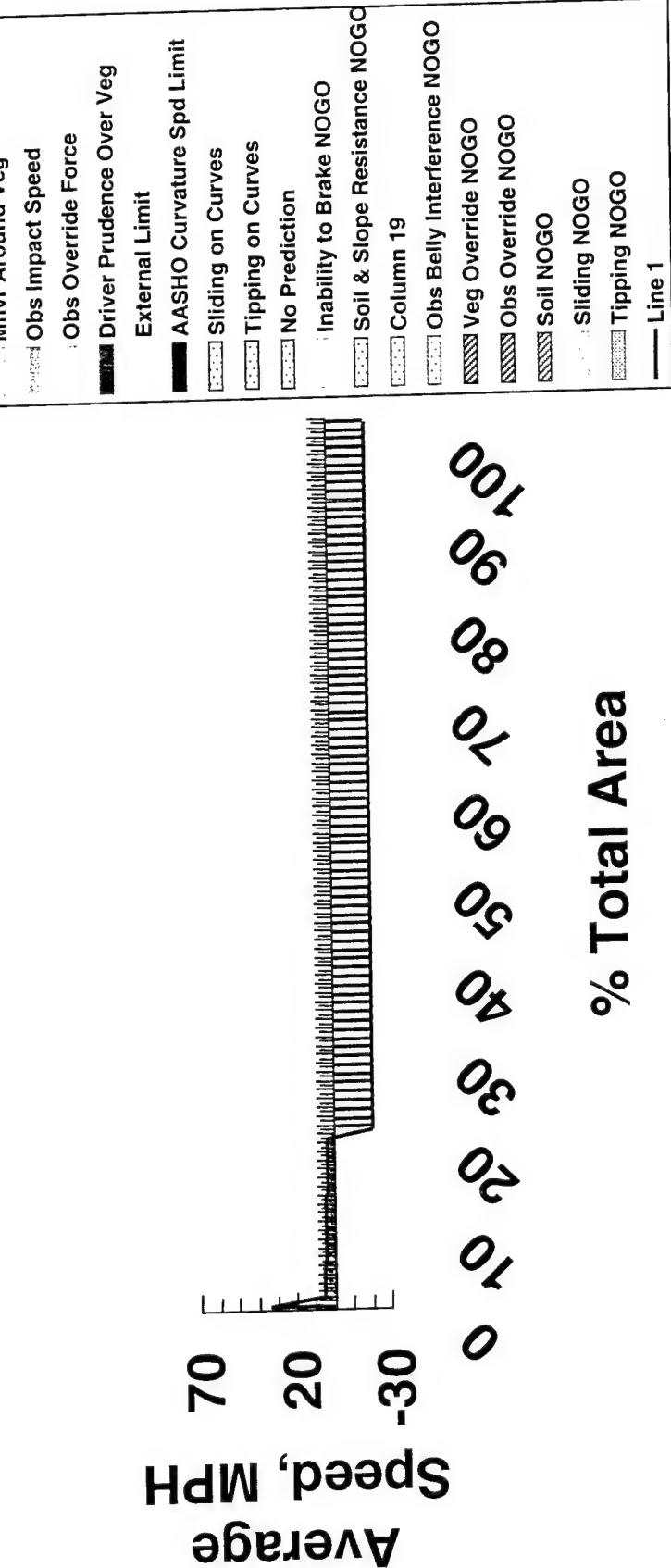
Waterways Experiment Station





PLS Speed/Reason Profile Mindanao, Philippines, Off-Road, 100 Iterations

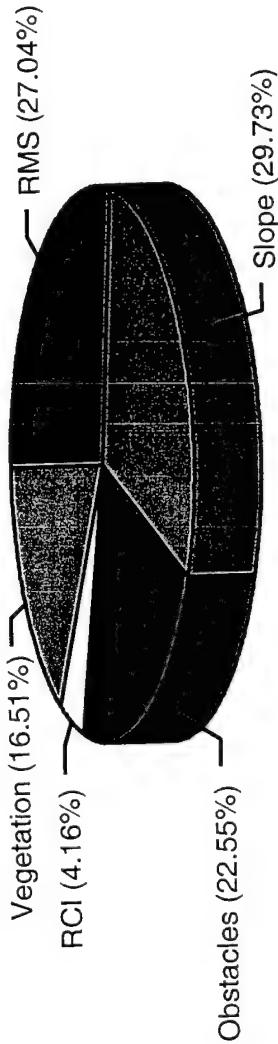
Wet Slippery 50th Percentile Speed ($\pm 25\%$)



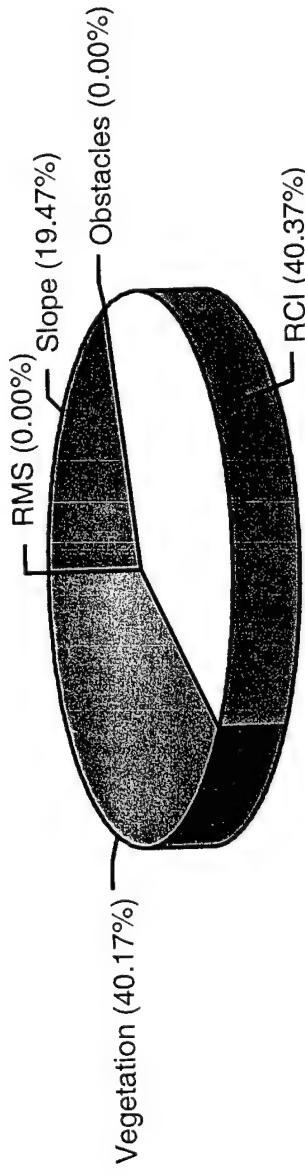
Significant Terrain Parameters for LVS

Philippines, Off-Road, 25% Variance

DRY NORMAL

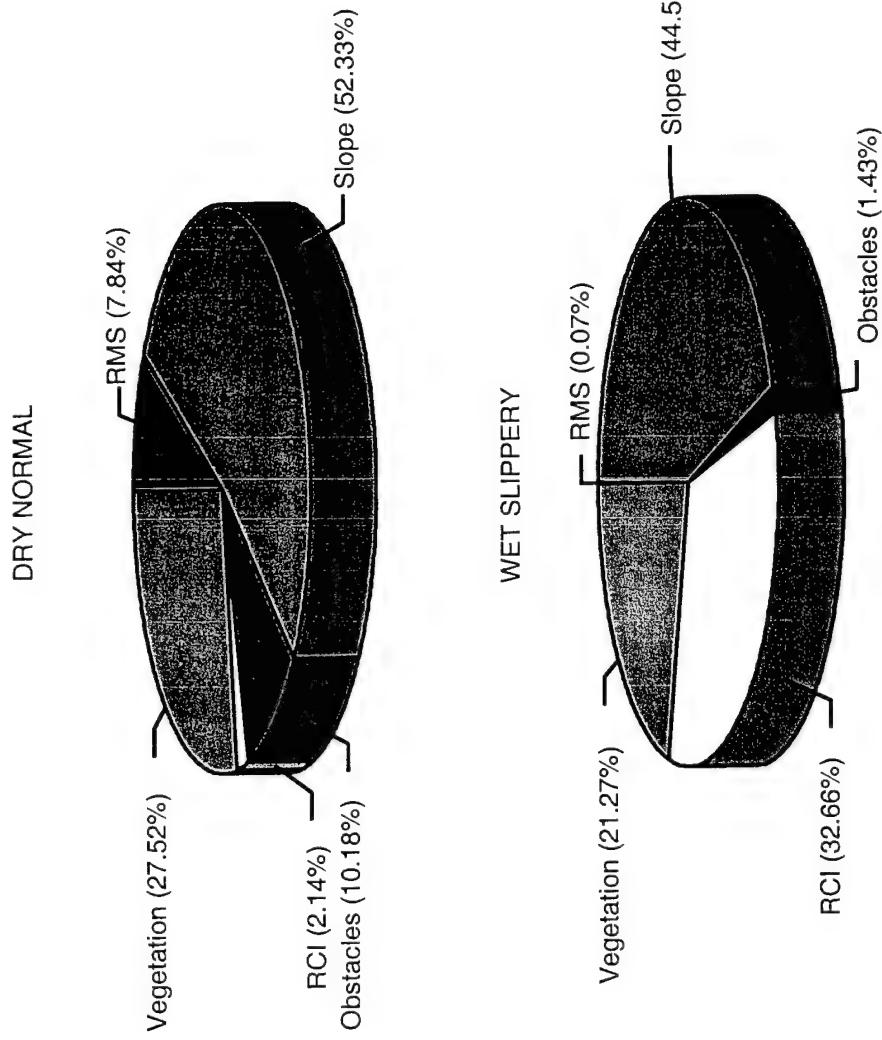


WET SLIPPERY



Significant Terrain Parameters for LVSR

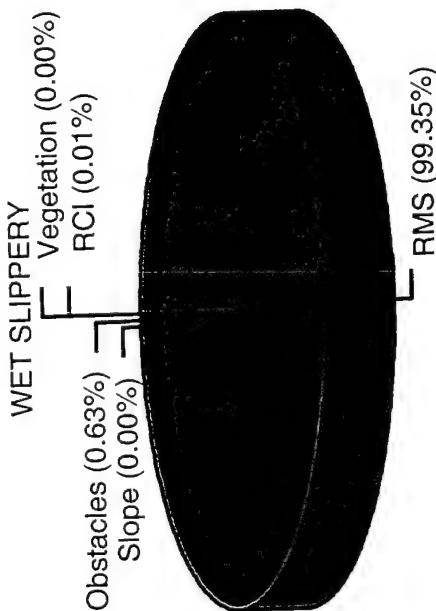
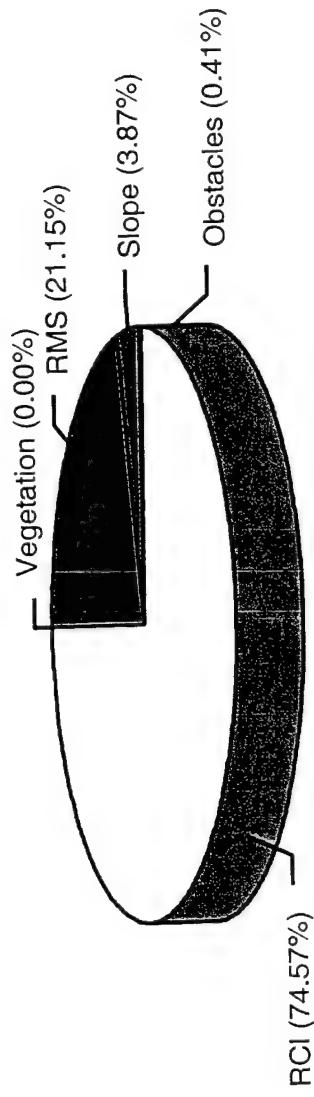
Korea, Off-Road, 25% Variance



Significant Terrain Parameters for LVS

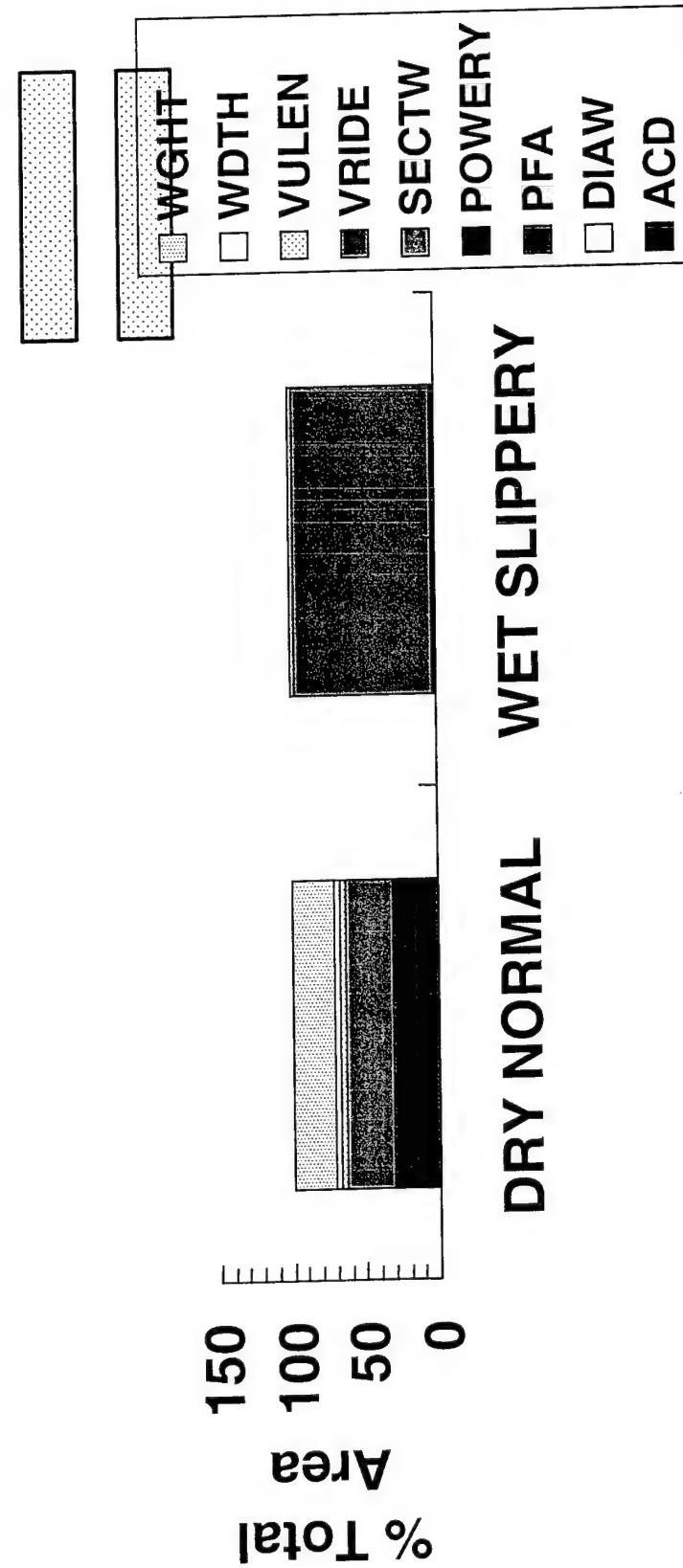
Kuwait, Off-Road, 25% Variance

DRY NORMAL



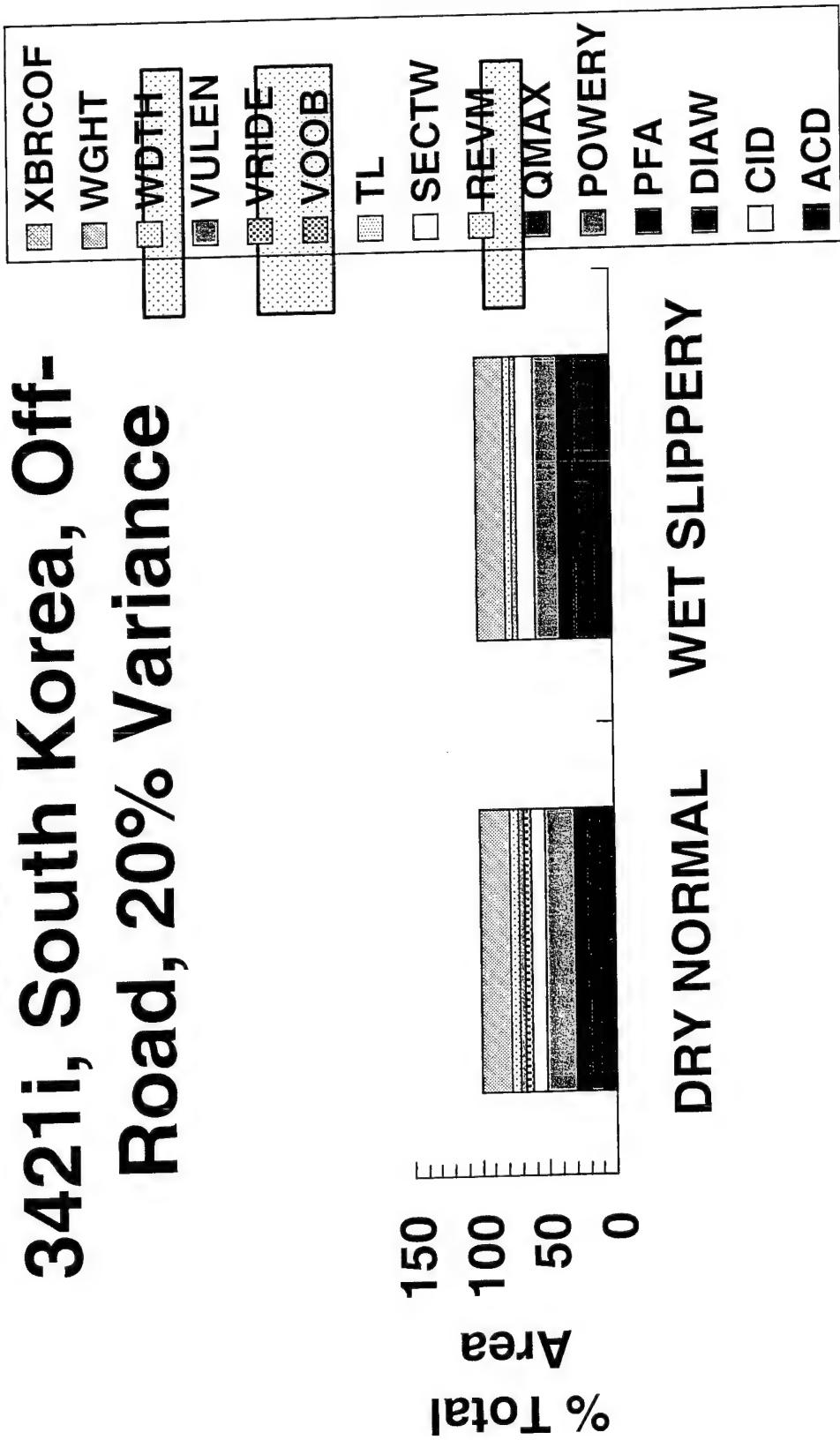
Significant LVSR Vehicle Parameters

Mindanao, Philippines, Off-Road, 20% Variance



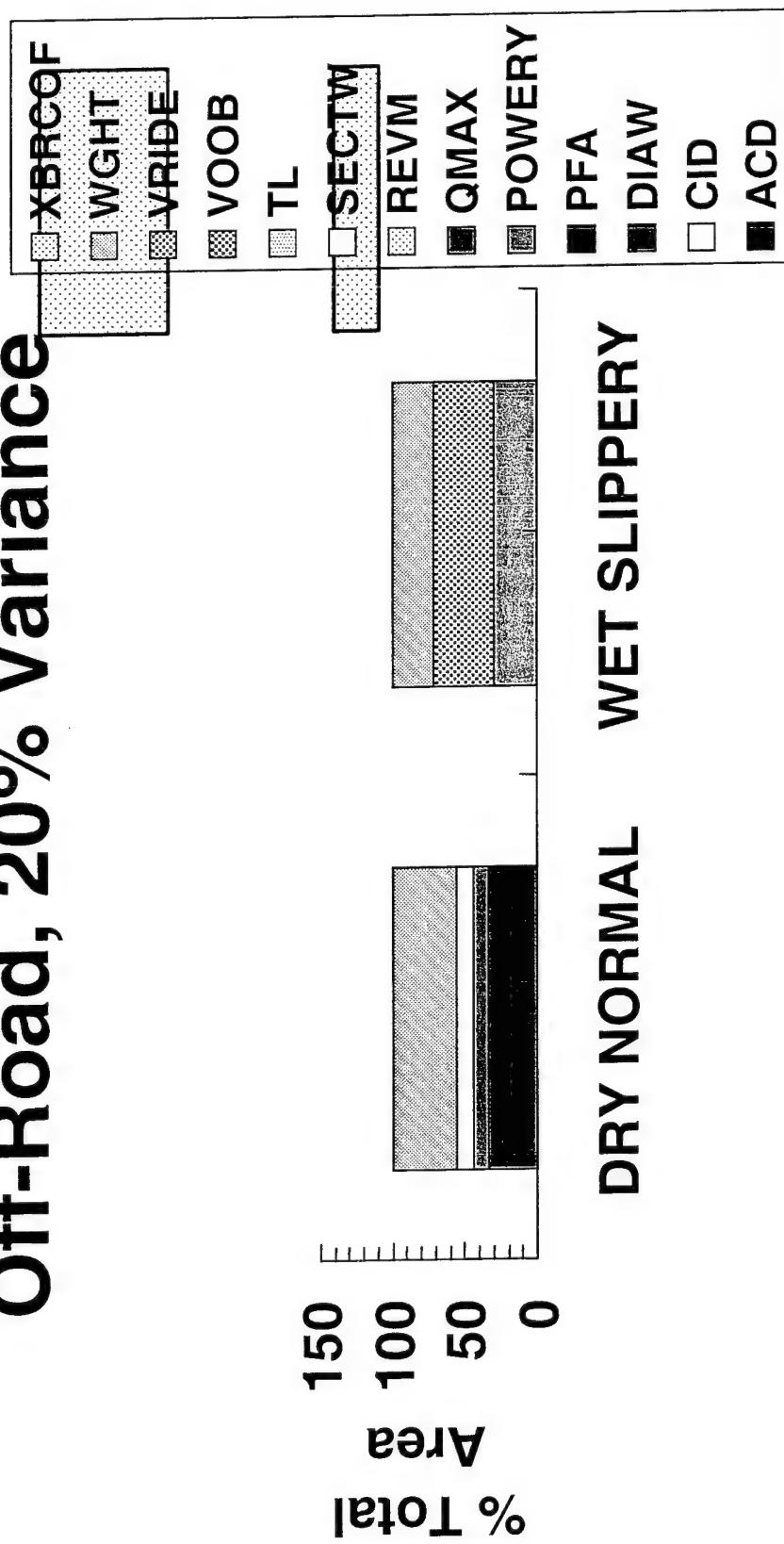
Significant LVS Parameters

3421i, South Korea, Off-Road, 20% Variance



Significant LVS Vehicle Parameters

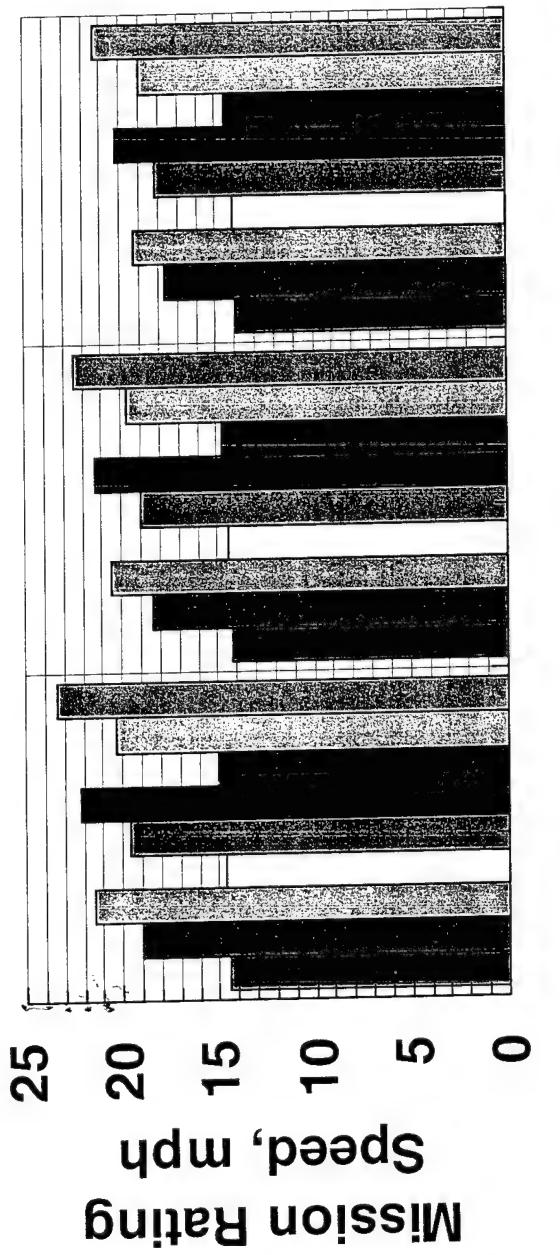
5546i, Saudi Arabia/Kuwait, Off-Road, 20% Variance



LVSR Mission Percentages

Percent of "Best" Terrain/Road Units		On		Percent Total Operating Distance on			
Primary Roads	Secondary Roads	Trails	Off-Road	Primary Roads	Secondary Roads	Trails	Off-Road
10	20	30	40	100	100	90	80
Philippines							
10	20	30	40	100	100	90	76
Korea							
10	20	30	40	100	100	90	80
Kuwait							
10	20	30	40	100	100	90	80

LVSR MSR Performance in the Philippines



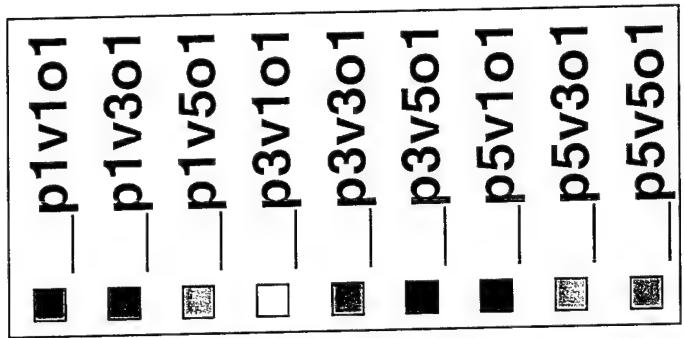
Weight

W1

W5

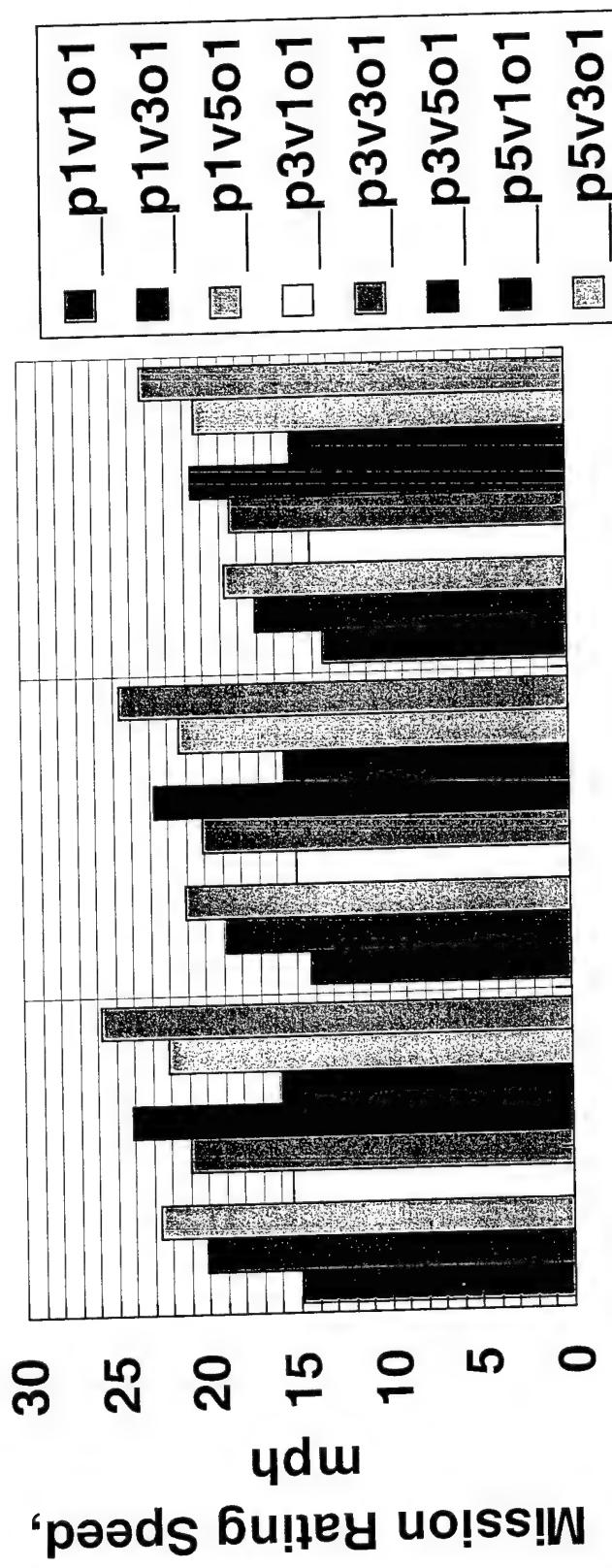
W3

Waterways Experiment Station



<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	v1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

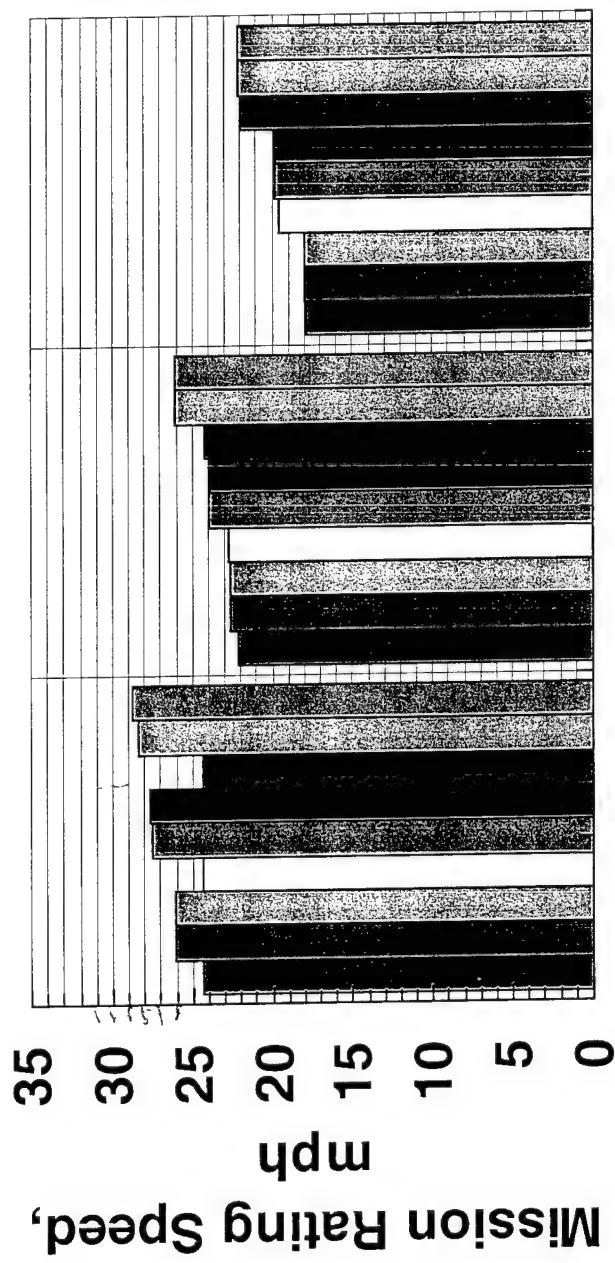
LVSR MSR Performance in Korea



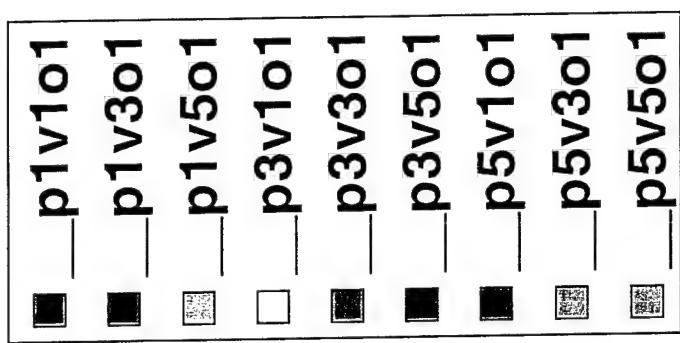
Waterways Experiment Station

<u>Payload</u>	<u>Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	W1	p1 = 445 hp	v1 = standard	v1 = standard
w3 = 16.5 ton	W3	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	W5	p5 = 600 hp	v5 = independent	

LVSR MSR Performance in Kuwait



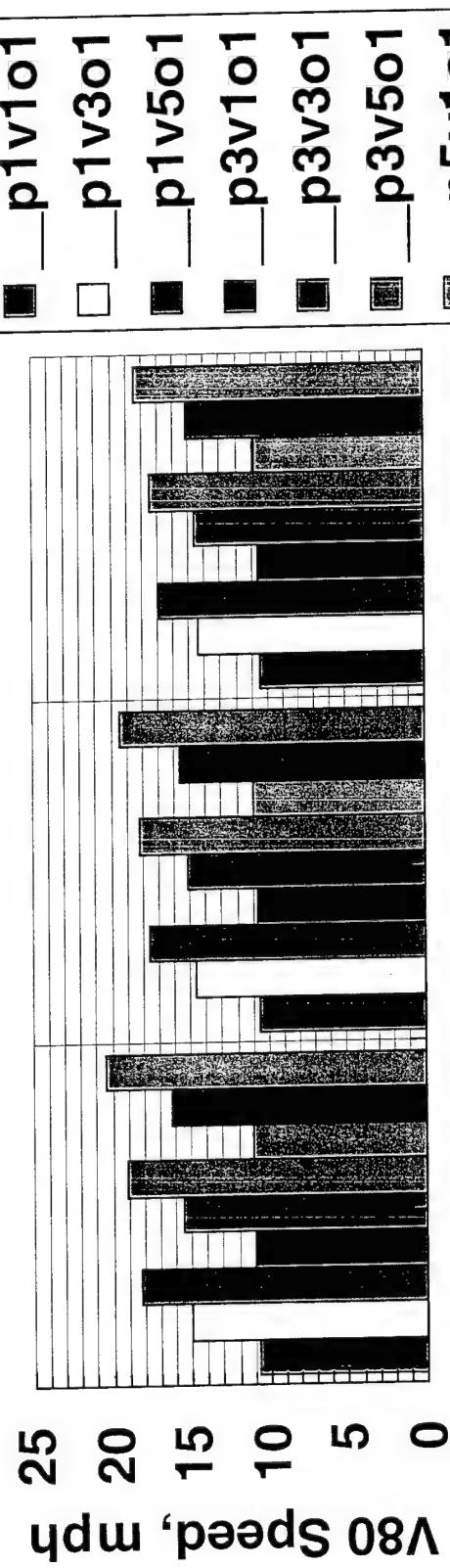
Waterways Experiment Station



Weight
w1 w3 w5

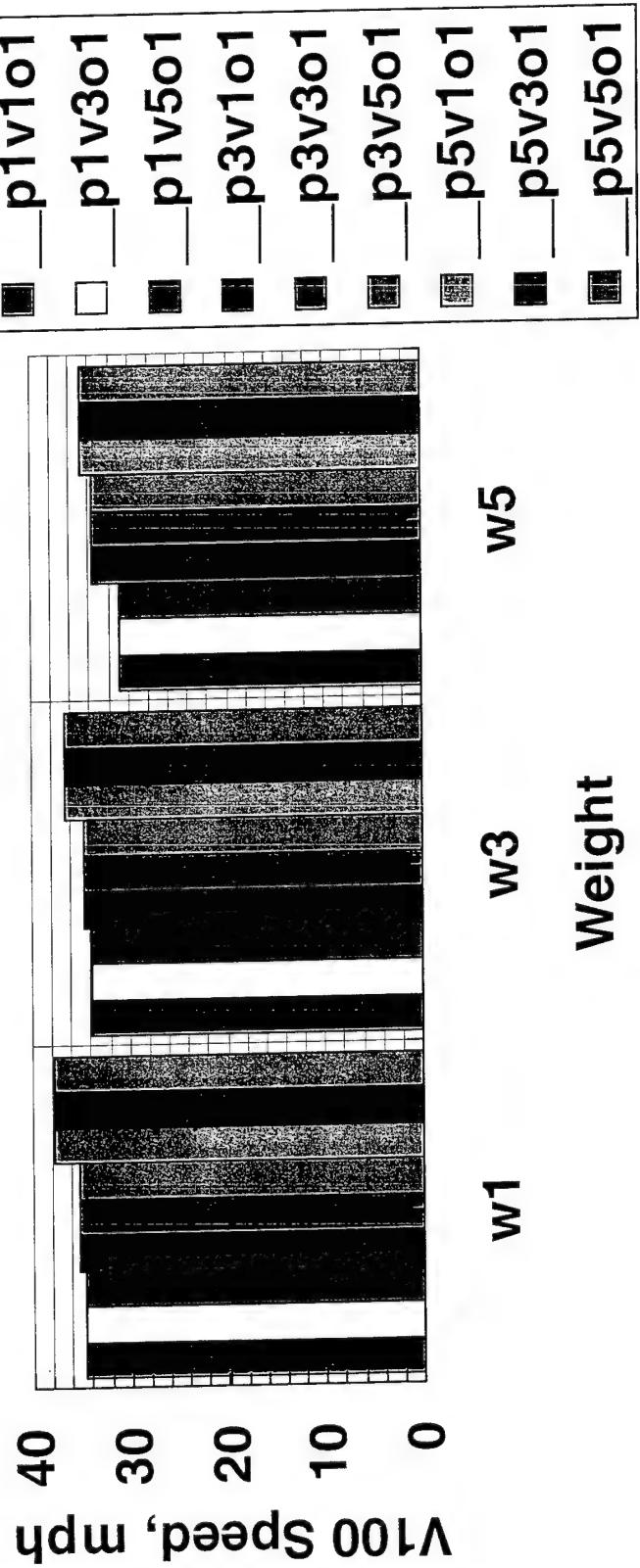
<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

LVSR Speed Performance in the Philippines Off-Road



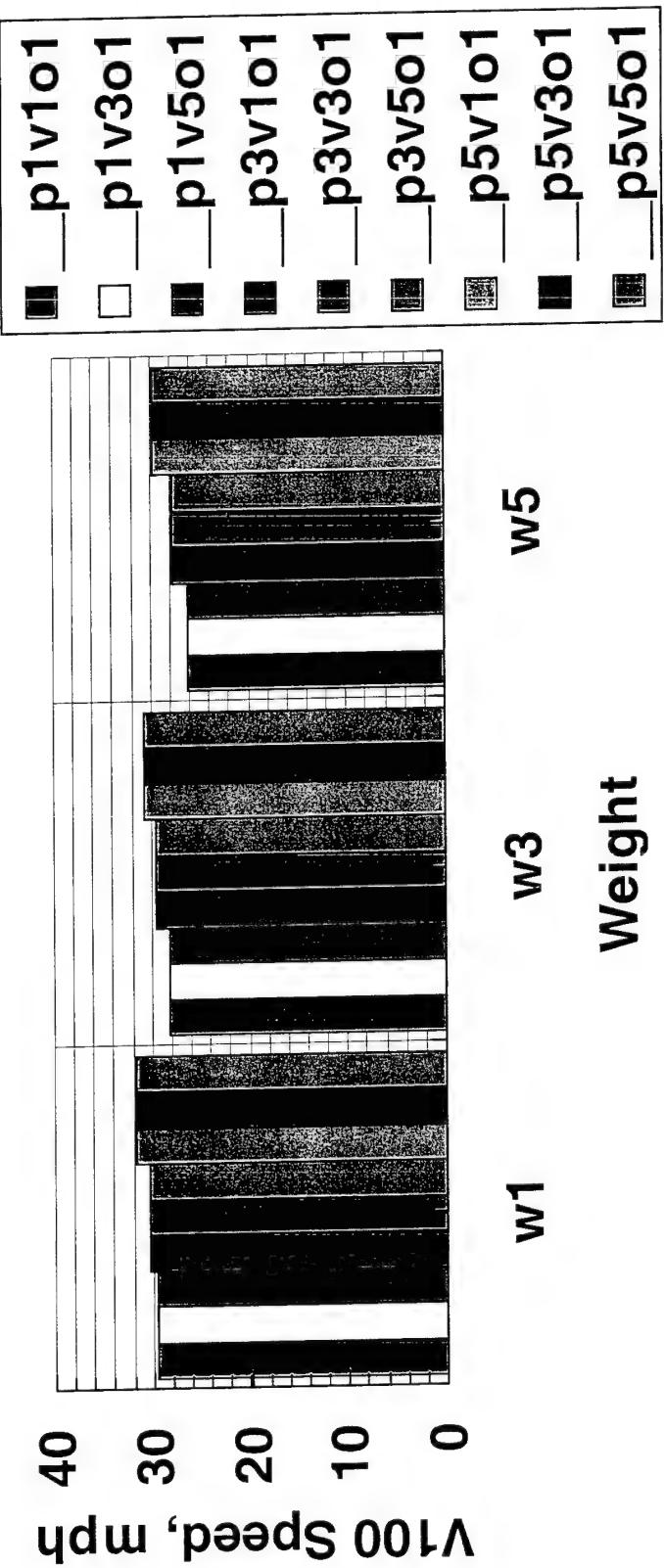
<u><u>Payload Weight</u></u>	<u><u>Engine Power</u></u>	<u><u>Suspension (Ride)</u></u>	<u><u>Suspension (Shock)</u></u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	v1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	v3 = improved standard
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	v5 = independent

LVSR Speed Performance in the Philippines Primary Roads



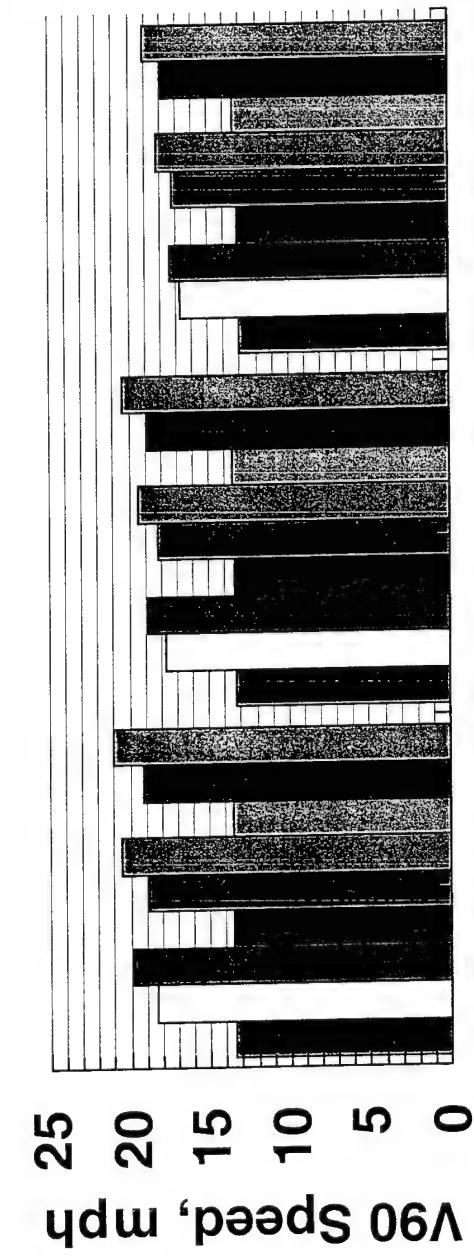
<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

LVSR Speed Performance in the Philippines Secondary Roads

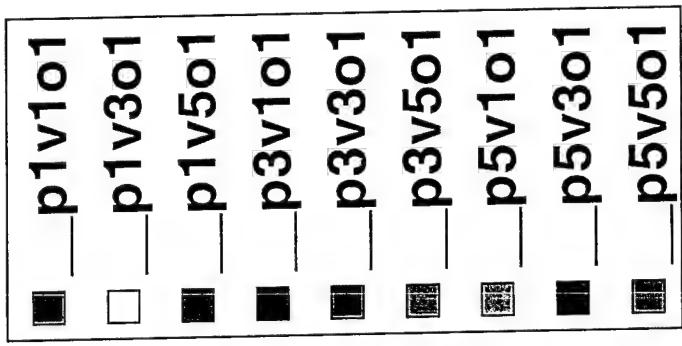


<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	v1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

LVSR Speed Performance in the Philippines Trails

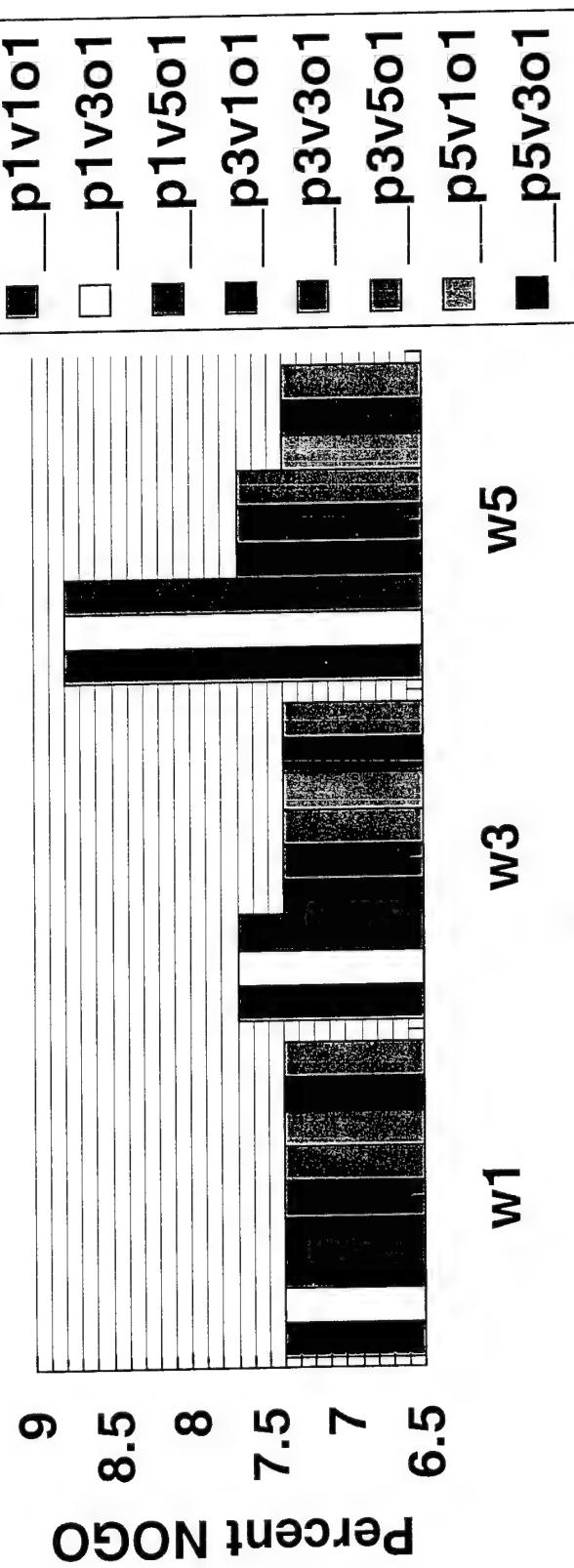


Waterways Experiment Station



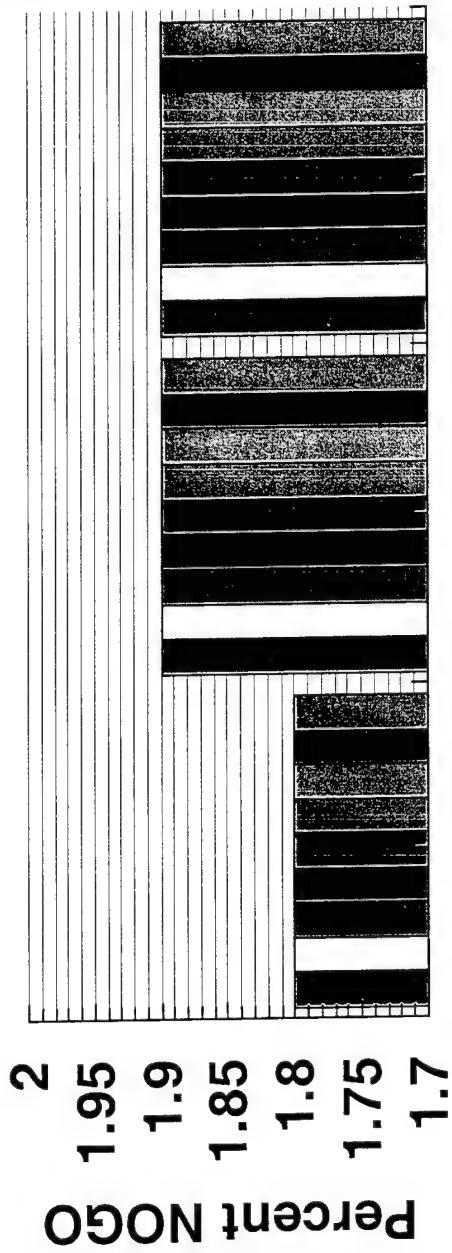
<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
W1 = 12.5 ton	p1 = 445 hp	v1 = standard	v1 = standard
W3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	v3 = improved standard
W5 = 22.5 ton	p5 = 600 hp	v5 = independent	v5 = independent

LVSR NOGO Performance in the Philippines Off-Road

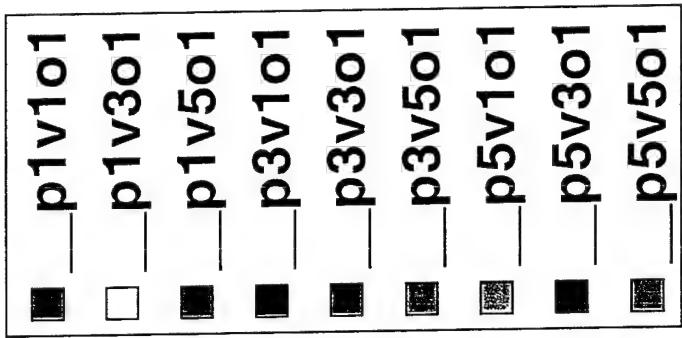


<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	v1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	v3 = improved standard
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	v5 = independent

LVSR NOGO Performance in the Philippines On-Road



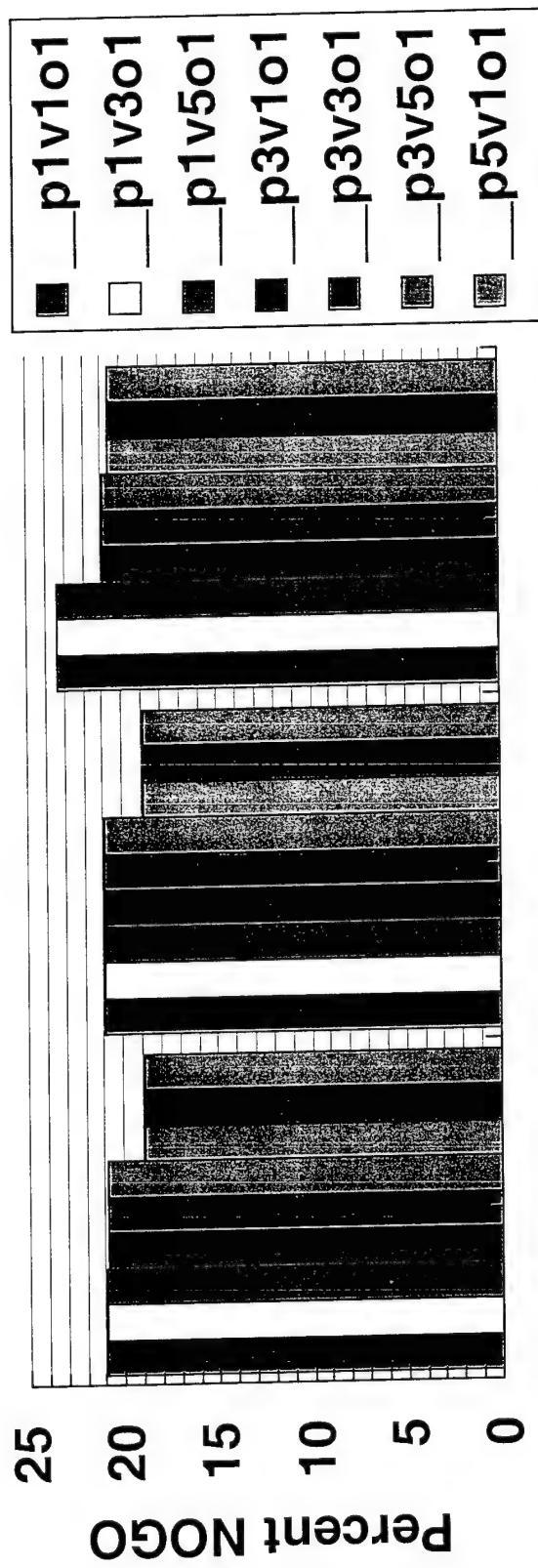
Waterways Experiment Station



w1 w3 w5
Weight

<u>Payload</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	o1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

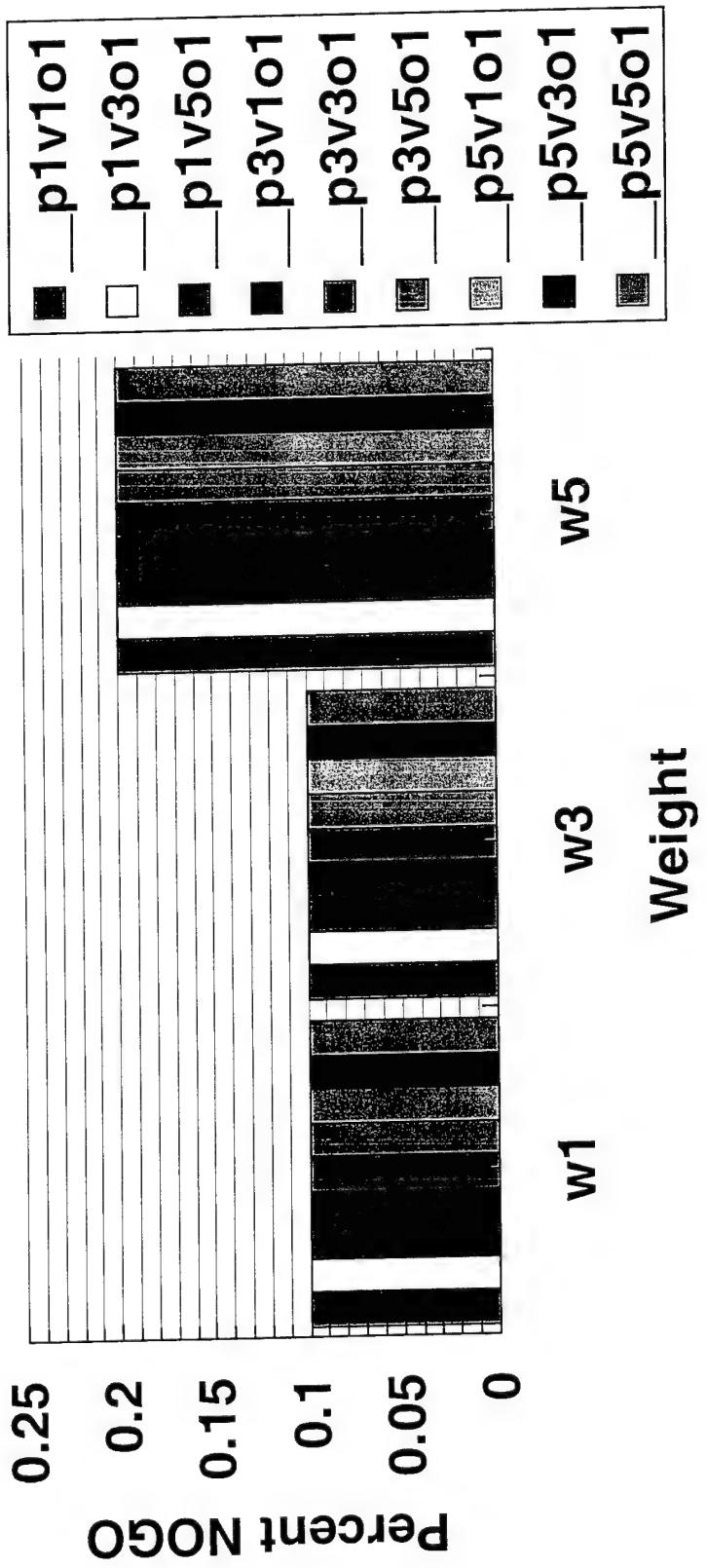
LVSR NOGO Performance in Korea Off-Road



Waterways Experiment Station

<u>Payload Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	p1 = 445 hp	v1 = standard	v1 = standard
w3 = 16.5 ton	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	p5 = 600 hp	v5 = independent	

LVSR NOGO Performance in Kuwait Off-Road

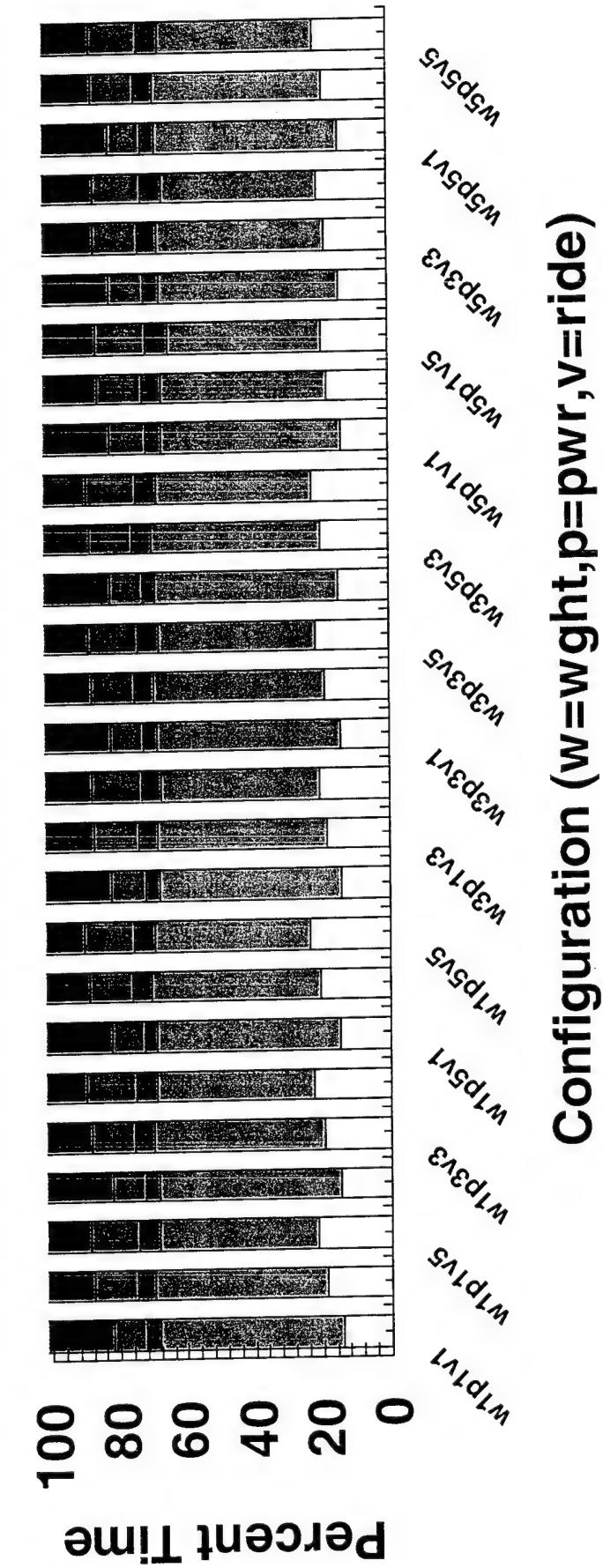


Waterways Experiment Station

<u>PayLoad</u>	<u>Weight</u>	<u>Engine Power</u>	<u>Suspension (Ride)</u>	<u>Suspension (Shock)</u>
w1 = 12.5 ton	w1	p1 = 445 hp	v1 = standard	v1 = standard
w3 = 16.5 ton	w3	p3 = 500 hp	v3 = improved standard	
w5 = 22.5 ton	w5	p5 = 600 hp	v5 = independent	

LVSR Percent Times Off-Road and On-Road

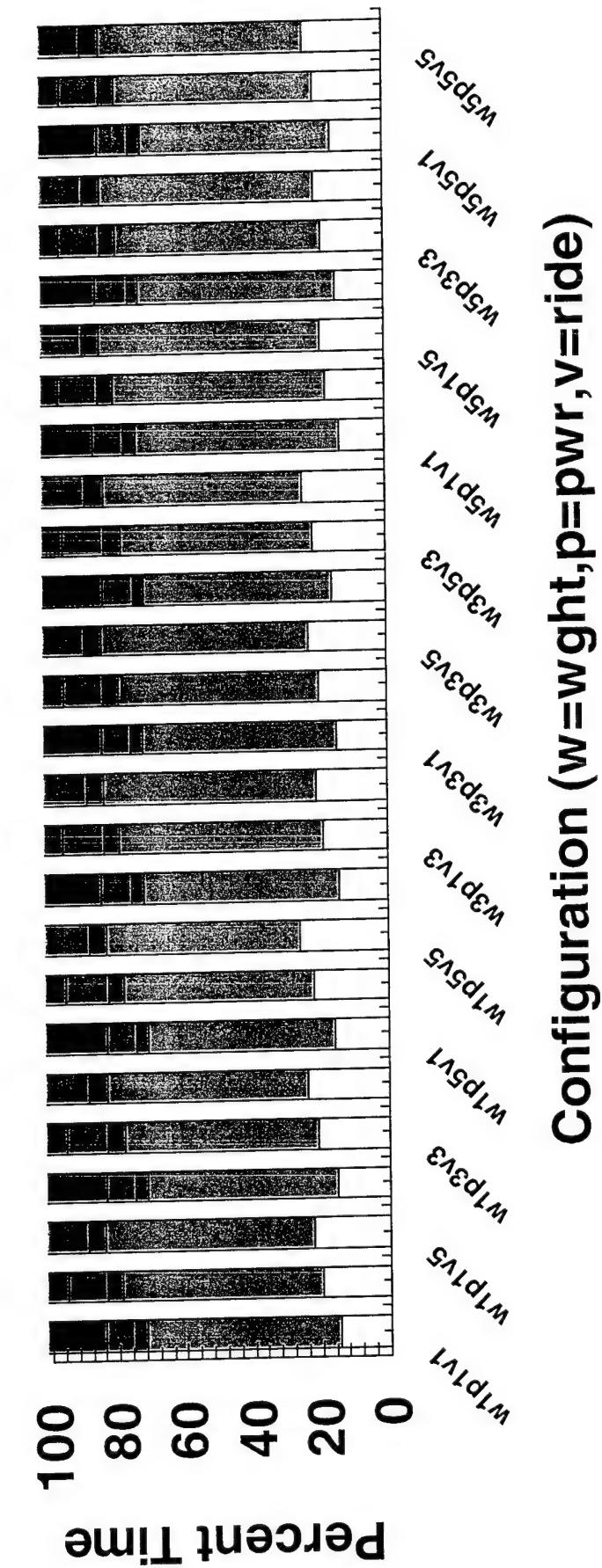
Philippines, Mindanao Dry Normal



Waterways Experiment Station

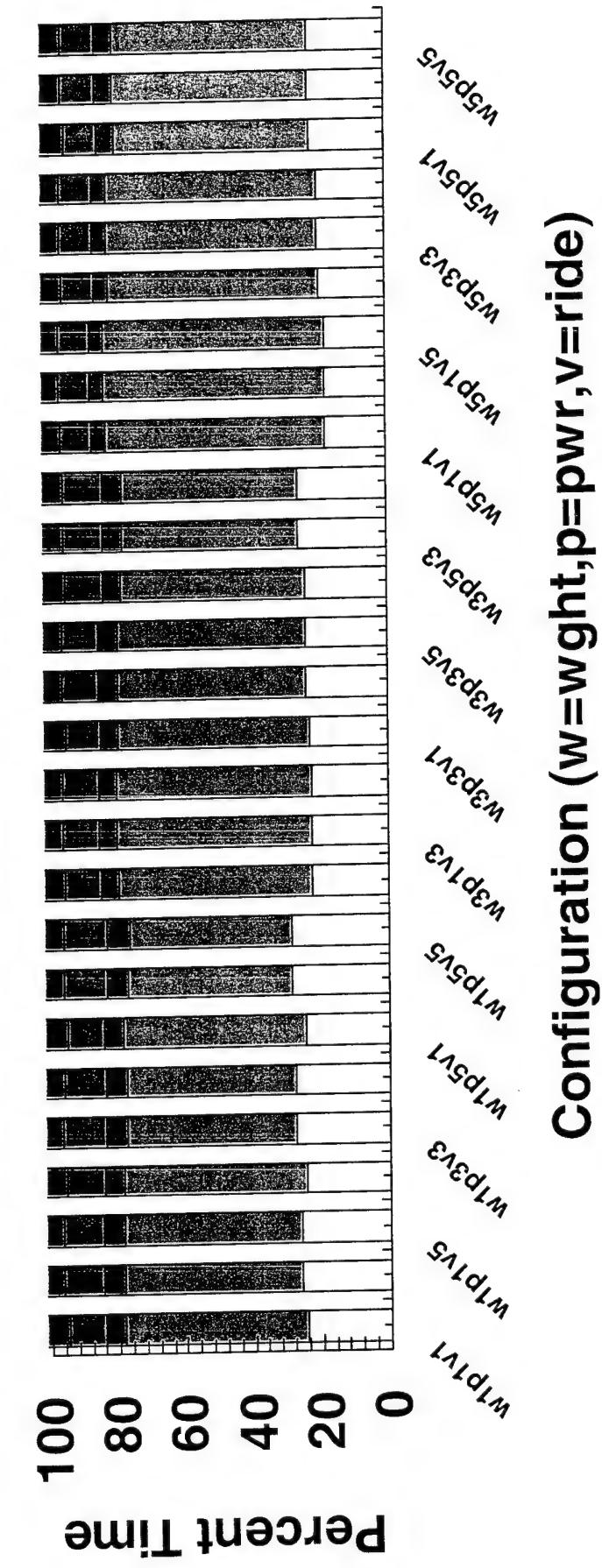
LVSR Percent Times Off-Road and On-Road

Korea, 3421i Dry Normal



LVSR Percent Times Off-Road and On-Road

Kuwait, 5546i Dry Normal



Response: MRS

Summary of Fit	
RSquare	0.978756
RSquare Adj	0.957774
Root Mean Square Error	0.838613
Mean of Response	20.07593
Observations (or Sum Wgts)	62

Parameter Estimates

Effect Test

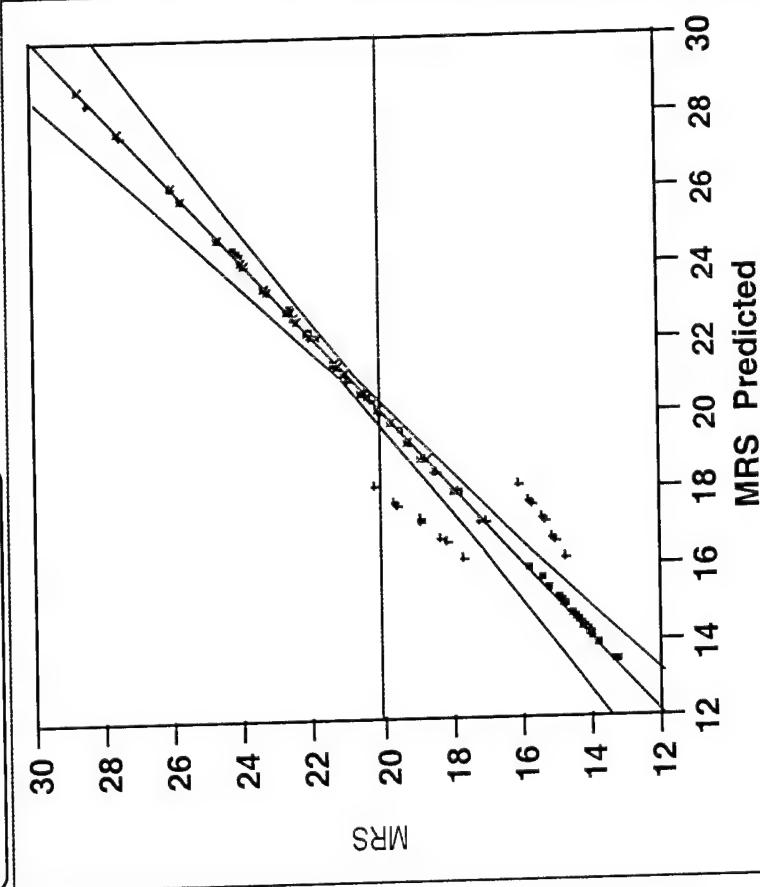
Source	Nparm	DF	Sum of Squares	F Ratio	Prob>F
Country	2	2	953.13000	677.6400	<.0001
Weight	2	2	296.84333	211.0446	<.0001
Country*Weight	4	4	141.73444	50.3840	<.0001
Power	2	2	132.25593	94.0291	<.0001
Country*Power	4	4	15.49407	5.5079	0.0006
Weight*Power	4	4	6.90296	2.4539	0.0523
Country*Weight*Power	8	8	5.08037	0.9030	0.5182
Ride	2	2	794.48481	564.8492	<.0001
Country*Ride	4	4	233.43407	82.9815	<.0001
Weight*Ride	4	4	22.88074	8.1337	<.0001
Country*Weight*Ride	8	8	4.69037	0.8337	0.5757
Power*Ride	4	4	13.82370	4.9141	0.0013
Country*Power*Ride	8	8	1.84519	0.3280	0.9530
Weight*Power*Ride	8	8	0.35963	0.0639	0.9998
Country*Weight*Power*Ride	16	16	1.55148	0.1379	1.0000

= significant interaction between factors (Prob >F is < .05)



= significant factor influencing mrs (Prob >F is < .05)

Whole-Model Test



Analysis of Variance

Source	DF	Sum of Squares	Mean Square	F Ratio
Model	80	2624.5111	32.8064	46.6482
Error	81	56.9650	0.7033	Prob>F
C Total	161	2681.4761		<.0001

